Generalized k-Center: Distinguishing Doubling and Highway Dimension

Andreas Emil Feldmann, Tung Anh Vu





Capacitated k-Center

Input

- ▶ graph G = (V, E) with edge lengths $\ell \colon E \to \mathbb{R}^+$,
- ▶ integer *k*,
- ightharpoonup capacities $c: V \to \mathbb{N}$.

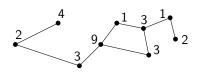


Figure: CKC input with k = 2.

Capacitated k-Center: Goal

Find $S \subseteq V$ and an assignment $\varphi \colon (V \setminus S) \to S$ such that

- $|S| \leq k$
- ▶ for every $u \in S$, $|\varphi^{-1}(u)| \le c(u)$, and
- $ightharpoonup \max_{v \in V \setminus S} \operatorname{dist}(v, \varphi(v))$ is minimal.

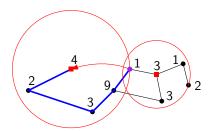


Figure: CKC solution for k = 2.

Capacitated k-Center: Goal

Find $S \subseteq V$ and an assignment $\varphi \colon (V \setminus S) \to S$ such that

- $|S| \leq k$
- ▶ for every $u \in S$, $|\varphi^{-1}(u)| \le c(u)$, and
- $ightharpoonup \max_{v \in V \setminus S} \operatorname{dist}(v, \varphi(v))$ is minimal.

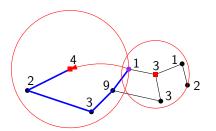


Figure: CKC solution for k = 2.

When c(u) = |V| for every $u \in V \Rightarrow k$ -CENTER.

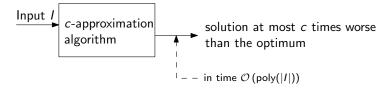
CAPACITATED k-CENTER is NP-hard.

 \Rightarrow cannot solve exactly in polynomial time assuming P \neq NP.

CAPACITATED k-CENTER is NP-hard.

 \Rightarrow cannot solve exactly in polynomial time assuming P \neq NP.

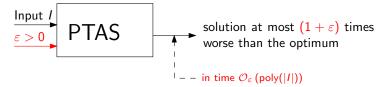
c-approximation algorithm



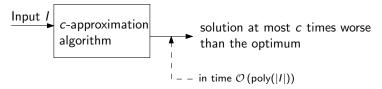
CAPACITATED k-CENTER is NP-hard.

 \Rightarrow cannot solve exactly in polynomial time assuming P \neq NP.

Polynomial-time approximation scheme



c-approximation algorithm

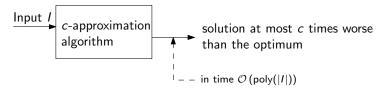


An, Bhaskara, Chekuri, Gupta, Madan, Svensson. 2015 There is a 9-approximation algorithm for $\rm C\kappa C$.

Cygan, Hajiaghayi, Khuller. 2012

There is no $(3 - \varepsilon)$ -approximation algorithm for CKC unless P = NP.

c-approximation algorithm



Cygan, Hajiaghayi, Khuller. 2012

There is no $(3 - \varepsilon)$ -approximation algorithm for CKC unless P = NP.

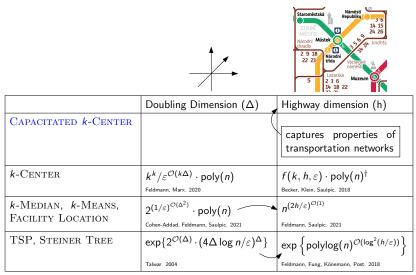
Question

Are there settings where we can overcome this lower bound? Planar graphs, Euclidean spaces, real world, ...

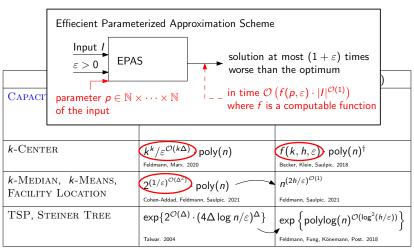




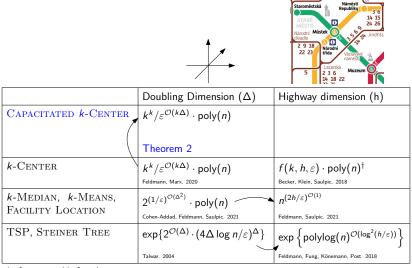
	Doubling Dimension (Δ)	
CAPACITATED k-CENTER	generalizes the dimension of ℓ_q spaces	
k-Center	$k^k/arepsilon^{\mathcal{O}(k\Delta)}\cdot poly(n)$ Feldmann, Marx. 2020	
k-Median, k-Means, Facility Location	$2^{(1/arepsilon)^{\mathcal{O}(\Delta^2)}} \cdot poly(n)$ Cohen-Addad, Feldmann, Saulpic. 2021	
TSP, STEINER TREE	$\exp\{2^{\mathcal{O}(\Delta)}\cdot (4\Delta\log n/\varepsilon)^{\Delta}\}$	



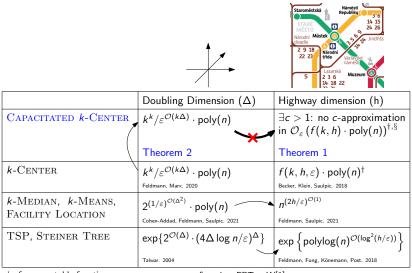
†: f: computable function



†: f: computable function



†: f: computable function



 \dagger : f: computable function

 $\S: unless FPT = W[1]$

▶ Let M = (X, dist) be a metric space.

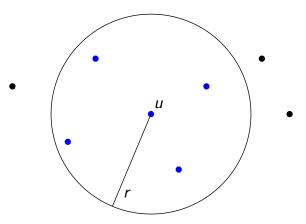
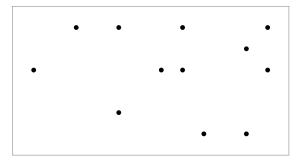


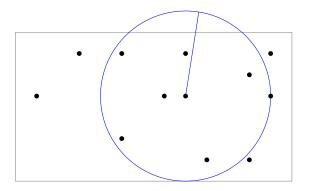
Figure: $B_r(u)$: Ball of radius r.

Doubling dimension $\Delta(M)$: smallest $\Delta \in \mathbb{N}$ such that



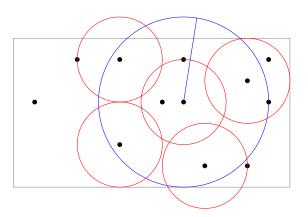
Doubling dimension $\Delta(M)$: smallest $\Delta \in \mathbb{N}$ such that

▶ the ball $B_r(u)$ for every $u \in X$ and every $r \in \mathbb{R}^+$



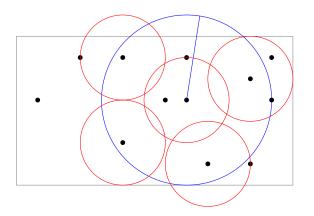
Doubling dimension $\Delta(M)$: smallest $\Delta \in \mathbb{N}$ such that

- ▶ the ball $B_r(u)$ for every $u \in X$ and every $r \in \mathbb{R}^+$
- ▶ is contained in $\bigcup_{v \in V} B_{r/2}(v)$ for some $V \subseteq X$ with $|V| \le 2^{\Delta}$.



Doubling dimension $\Delta(M)$: smallest $\Delta \in \mathbb{N}$ such that

- ▶ the ball $B_r(u)$ for every $u \in X$ and every $r \in \mathbb{R}^+$
- ▶ is contained in $\bigcup_{v \in V} B_{r/2}(v)$ for some $V \subseteq X$ with $|V| \le 2^{\Delta}$.



 \rightsquigarrow d-dimensional ℓ_q metrics have doubling dimension $\mathcal{O}(d)$.



Highway Dimension: Shortest Path Cover

- ▶ Let *G* be an edge-weighted graph and fix a *scale* $r \in \mathbb{R}^+$.
- ▶ Let \mathcal{P}_r be the set of paths of G such that
 - they are a shortest path between their endpoints,
 - ightharpoonup their length is more than r and at most 2r.



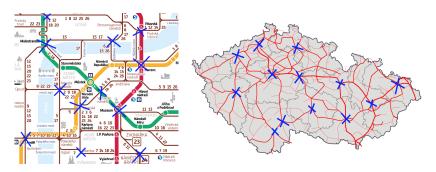
(a) Metro and tram network in Prague city center.



(b) Czech railway network.

Highway Dimension: Shortest Path Cover

- ▶ Let *G* be an edge-weighted graph and fix a *scale* $r \in \mathbb{R}^+$.
- ▶ Let \mathcal{P}_r be the set of paths of G such that
 - they are a shortest path between their endpoints,
 - ightharpoonup their length is more than r and at most 2r.



The shortest path cover $SPC_r(G)$ is a hitting set¹ for \mathcal{P}_r .

¹For every $P \in \mathcal{P}_r$ we have $P \cap SPC_r(G) \neq \emptyset$.

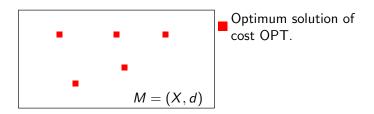
Highway Dimension

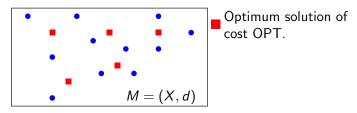
highway dimension of an edge-weighted graph G:

- smallest integer h such that,
- ▶ for any scale $r \in \mathbb{R}^+$,
- ▶ there exists $H := SPC_r(G)$ so that,
- ▶ $|H \cap B_{2r}(u)| \le h$ for every $u \in V(G)$.

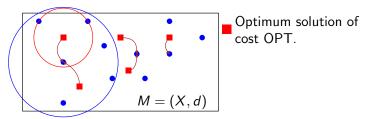




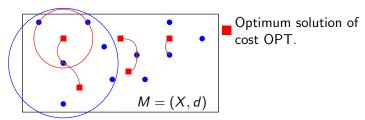




- Net: $Y \subseteq X$ such that
 - $\forall x \in X \exists y \in Y : d(x,y) \le \varepsilon \text{ OPT, and}$
 - $\forall y_1 \neq y_2 \in Y : d(y_1, y_2) > \varepsilon \text{ OPT}.$

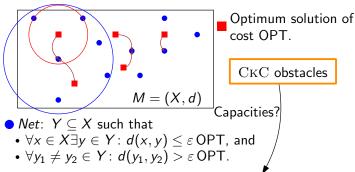


- Net: $Y \subseteq X$ such that
 - $\forall x \in X \exists y \in Y : d(x,y) \leq \varepsilon \text{ OPT, and }$
 - $\forall y_1 \neq y_2 \in Y : d(y_1, y_2) > \varepsilon \text{ OPT}.$
- Replace every optimum center by its nearest net point.
 - \Rightarrow We get a $(1+\varepsilon)$ -approximate solution.



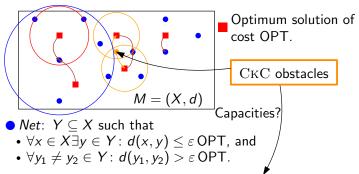
- Net: $Y \subseteq X$ such that
 - $\forall x \in X \exists y \in Y : d(x,y) \leq \varepsilon \text{ OPT, and}$
 - $\forall y_1 \neq y_2 \in Y : d(y_1, y_2) > \varepsilon \text{ OPT}.$
- Replace every optimum center by its nearest net point.
- \Rightarrow We get a $(1+\varepsilon)$ -approximate solution.
- It can be shown that $|Y| \leq k(1/\varepsilon)^{\mathcal{O}(\Delta)}$.
- \Rightarrow Guess the k-tuple near the optimum centers to get an EPAS with parameters k, ε , and Δ .

CKC algorithm obstacles



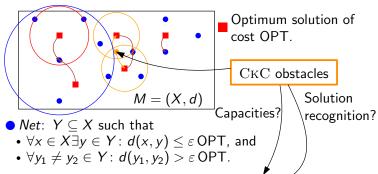
- Replace every optimum center by its nearest net point.
 - \Rightarrow We get a $(1+\varepsilon)$ -approximate solution.
- It can be shown that $|Y| \leq k(1/\varepsilon)^{\mathcal{O}(\Delta)}$.
- \Rightarrow Guess the k-tuple near the optimum centers to get an EPAS with parameters k, ε , and Δ .

CKC algorithm obstacles



- Replace every optimum center by its nearest net point.
 - \Rightarrow We get a $(1+\varepsilon)$ -approximate solution.
- It can be shown that $|Y| \leq k(1/\varepsilon)^{\mathcal{O}(\Delta)}$.
- \Rightarrow Guess the k-tuple near the optimum centers to get an EPAS with parameters k, ε , and Δ .

CKC algorithm obstacles



- Replace every optimum center by its nearest net point.
 - \Rightarrow We get a $(1+\varepsilon)$ -approximate solution.
- It can be shown that $|Y| \leq k(1/\varepsilon)^{\mathcal{O}(\Delta)}$.
- \Rightarrow Guess the k-tuple near the optimum centers to get an EPAS with parameters k, ε , and Δ .

Conclusion

	Doubling Dimension (Δ)	Highway dimension (h)
CAPACITATED k-CENTER	$k^k/arepsilon^{\mathcal{O}(k\Delta)}\cdot\operatorname{poly}(n)$	$\exists c>1$: no c -approximation in $\mathcal{O}_{arepsilon}(f(k,h)\cdot poly(n))^{\dagger,\S}$
	Theorem 2	Theorem 1
k-Center	$k^k/\varepsilon^{\mathcal{O}(k\Delta)}\cdot poly(n)$	$f(k, h, \varepsilon) \cdot poly(n)^{\dagger}$
	Feldmann, Marx. 2020	Becker, Klein, Saulpic. 2018
k-Median, k-Means, Facility Location	$2^{(1/\varepsilon)^{\mathcal{O}(\Delta^2)}} \cdot poly(n)$	$n^{(2h/\varepsilon)^{\mathcal{O}(1)}}$
FACILITY LOCATION	Cohen-Addad, Feldmann, Saulpic. 2021	Feldmann, Saulpic. 2021
TSP, STEINER TREE	$\exp\{2^{\mathcal{O}(\Delta)}\cdot(4\Delta\log n/\varepsilon)^{\Delta}\}$	$\exp\left\{polylog(n)^{\mathcal{O}(\log^2(h/\varepsilon))}\right\}$
	Talwar. 2004	Feldmann, Fung, Könemann, Post. 2018

 \dagger : f: computable function

 $\S\colon \mathsf{unless}\;\mathsf{FPT} = \mathsf{W[1]}$

Conclusion

	Doubling Dimension (Δ)	Highway dimension (h)
CAPACITATED k-CENTER	$k^k/arepsilon^{\mathcal{O}(k\Delta)}\cdot poly(n)$	$\exists c>1$: no c -approximation in $\mathcal{O}_{arepsilon}(f(k,h)\cdot poly(n))^{\dagger,\S}$
	Theorem 2	Theorem 1
k-Center	$k^k/arepsilon^{\mathcal{O}(k\Delta)}\cdot poly(n)$	$f(k, h, \varepsilon) \cdot \operatorname{poly}(n)^{\dagger}$
	Feldmann, Marx. 2020	Becker, Klein, Saulpic. 2018
k-MEDIAN, k-MEANS,	$2^{(1/\varepsilon)^{\mathcal{O}(\Delta^2)}} \cdot poly(n)$	$n^{(2h/\varepsilon)^{\mathcal{O}(1)}}$
FACILITY LOCATION	Cohen-Addad, Feldmann, Saulpic. 2021	Feldmann, Saulpic. 2021
TSP, STEINER TREE	$\exp\{2^{\mathcal{O}(\Delta)}\cdot(4\Delta\log n/\varepsilon)^{\Delta}\}$	$\exp\left\{polylog(n)^{\mathcal{O}(\log^2(h/\varepsilon))}\right\}$
	Talwar. 2004	Feldmann, Fung, Könemann, Post. 2018

†: f: computable function

 $\S: unless FPT = W[1]$

Thank you for your attention!

Questions, comments, ...?