

- Locally indistinguishable from the plane.
 - Every point has a neighborhood that looks like an open disk.
- Not too complicated: can be covered by finitely many such small neighborhoods.
- Connected.

Definition

A **surface** is a compact connected 2-dimensional manifold without a boundary.

- Locally indistinguishable from the plane.
 - Every point has a neighborhood that looks like an open disk.
- Not too complicated: can be covered by finitely many such small neighborhoods.
- Connected.

Q: Which of the following spaces are surfaces?

- sphere
- torus
- plane
- closed disk (circle and its interior)

Definition

A function $f : X \rightarrow Y$ between topological spaces is a **homeomorphism** if f is bijective and both f and f^{-1} are continuous. If there exists a homeomorphism from X to Y , we say X and Y are **homeomorphic**.

Observation

If f is a homeomorphism of surfaces, then

- *$f(\text{simple continuous curve}) = \text{simple continuous curve}$*
- *$f(\text{drawing of } G) = \text{drawing of } G$*

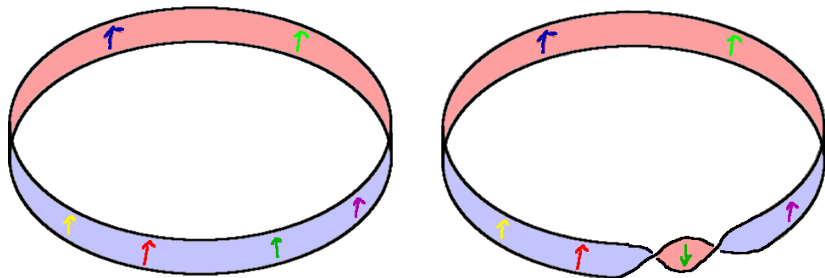
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- Torus and the surface of a coffee mug are homeomorphic.
- The cylinder and the twice-twisted band are homeomorphic.
- The cylinder and the once-twisted band (the Möbius band) are not homeomorphic.

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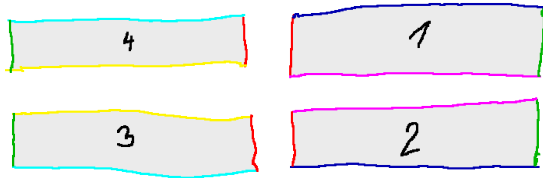
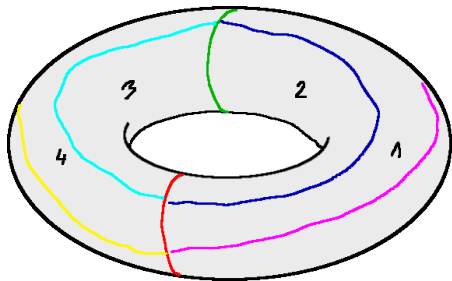
A net of a surface is a graph drawn in the surface so that every face is homeomorphic to an open disk.

Claim

Every surface has a net.

We can

- cut the surface along a net and
- glue it back together from the resulting polygons.

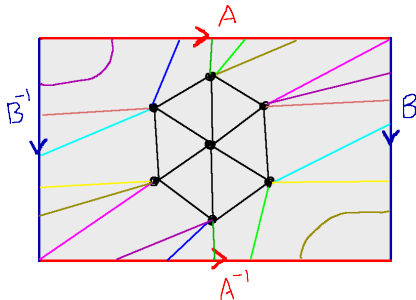


Observation

If G is a net and e is incident with two different faces of G , then $G - e$ is a net.

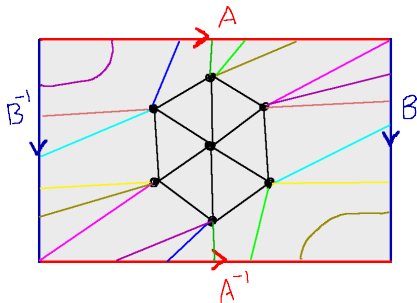
Corollary

Every surface has a net with only one face. Equivalently, every surface can be obtained by gluing pairs of edges on a single polygon.



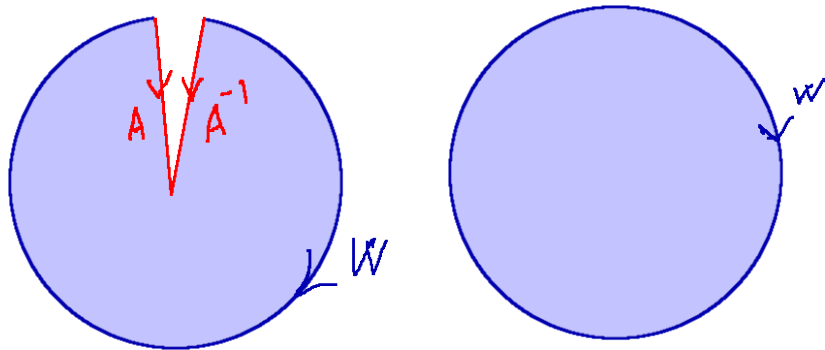
- Arrows indicate the direction of gluing.
- A : Clockwise arrow, A^{-1} : counterclockwise arrow.

$ABA^{-1}B^{-1}$:



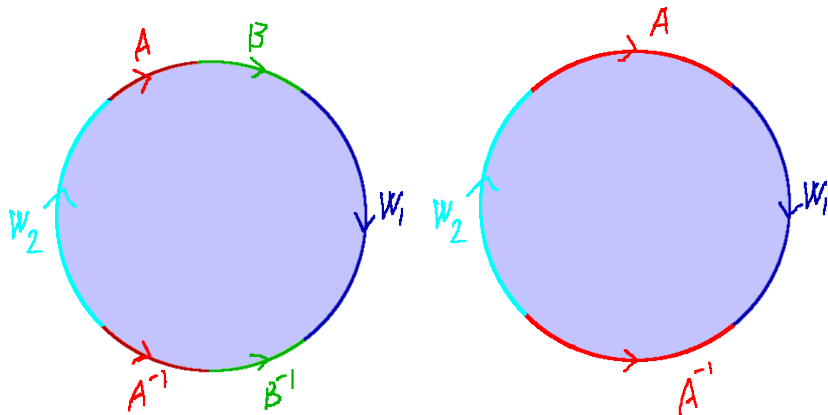
Observation

- $AA^{-1}w$ and w represent the same surface.
- $ABw_1B^{-1}A^{-1}w_2$ and $Aw_1A^{-1}w_2$ represent the same surface.
- Aw_1Aw_2 and $AAw_2w_1^{-1}$ represent the same surface.



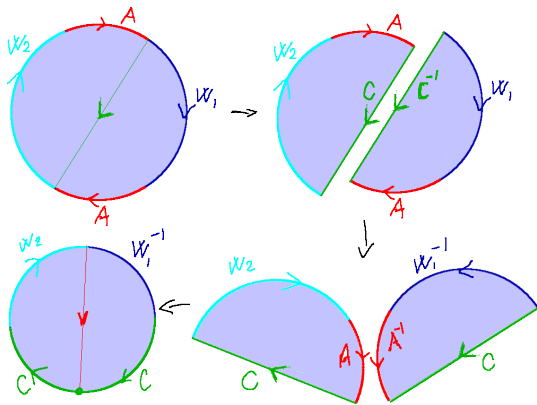
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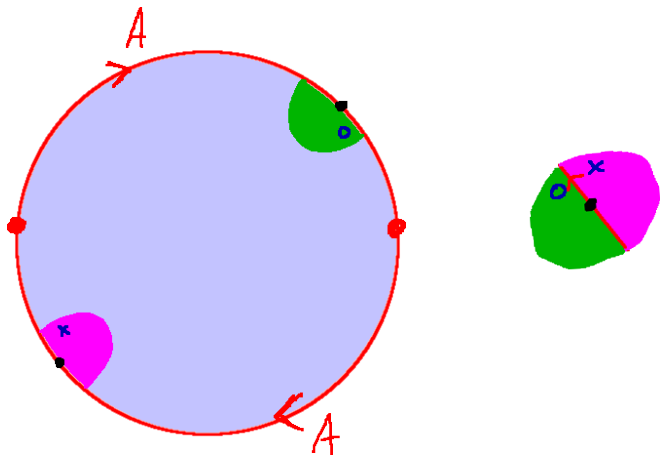
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Q: Two of these expressions represent the same surface; which two?

$$ABA^{-1}B^{-1}, ABA^{-1}B, AABB$$

Does AA represent a surface?



Lemma

If G_1 and G_2 are nets of the same surface, then

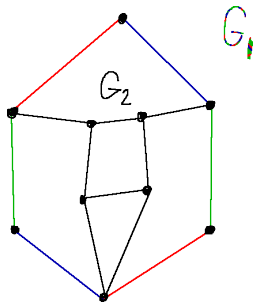
$$|E(G_1)| - |V(G_1)| - |F(G_1)| = |E(G_2)| - |V(G_2)| - |F(G_2)|.$$

WLOG:

- Drawings of G_1 and G_2 intersect in finite number of points (nontrivial!)
- G_1 intersects G_2 only in vertices
 - subdividing edges: both $|E|$ and $|V|$ increase by 1
- $G_1 \subseteq G_2$
 - Compare G_1 vs. $G_1 \cup G_2$ vs. G_2
- G_1 has exactly one face
 - deleting edge between distinct faces: both $|E|$ and $|F|$ decrease by 1

G' : Plane graph obtained by taking

- polygonal representation corresponding to the net G_1 and
- the drawing of G_2 in the polygon.



$$|F(G')| = |F(G_2)| + 1 = |F(G_2)| - |F(G_1)| + 2$$

$$|E(G')| = |E(G_2)| + |E(G_1)|$$

$$|V(G')| = |V(G_2)| - |V(G_1)| + 2|E(G_1)|$$

$$0 = |E(G')| - |F(G')| - |V(G')| + 2$$

$$= (|E(G_2)| - |V(G_2)| - |F(G_2)|)$$

$$- (|E(G_1)| - |V(G_1)| - |F(G_1)|)$$

Definition

The **Euler genus** of a surface with a net G is

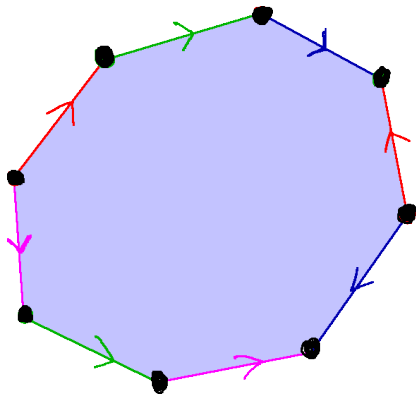
$$|E(G)| - |V(G)| - |F(G)| + 2.$$

Observation

Let G be a net of a surface Σ with exactly one face.

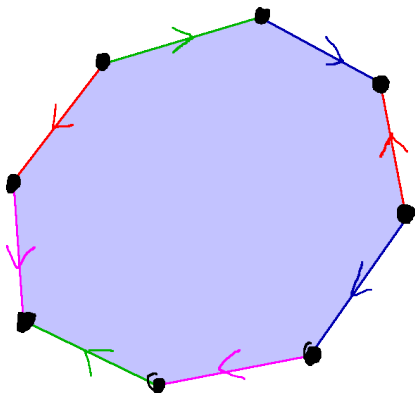
- If $\Sigma = \text{sphere}$, then G is a tree, and thus the sphere has Euler genus 0.*
- Otherwise, if $|V(G)|$ is minimum possible, then G has minimum degree at least two, and thus Σ has positive Euler genus.*

Example:



4 edges, 1 face, 2 vertices \rightarrow Euler genus 3.

Q: Determine the Euler genus of the following surface:



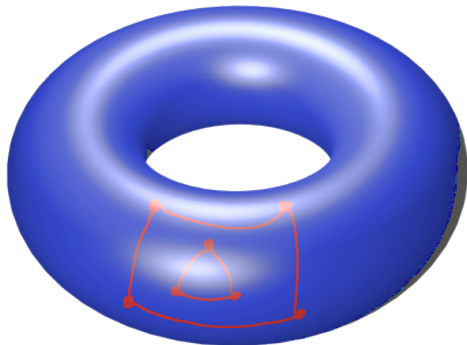
Theorem (Generalized Euler formula)

If a graph G is drawn in a surface of Euler genus g , then

$$|E(G)| \leq |V(G)| + |F(G)| + g - 2.$$

Proof.

Add edges to G to extend it to a net. □



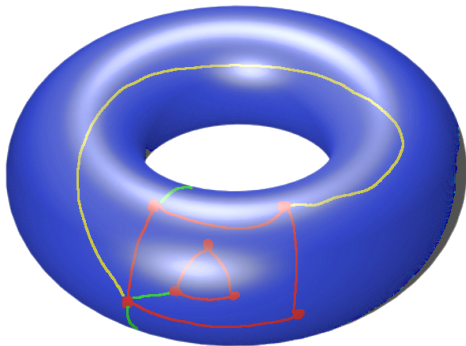
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Add edges to G to extend it to a net. □

Corollary

If a simple graph G is drawn in a surface of Euler genus g and $|V(G)| \geq 3$, then $|E(G)| \leq 3|V(G)| + 3g - 6$.

Proof.

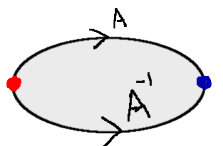
$$2|E(G)| \geq 3|F(G)| \geq 3(|E(G)| - |V(G)| - g + 2)$$

□

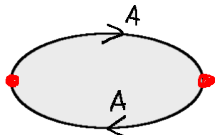
Corollary

K_8 cannot be drawn in the torus (Euler genus $g = 2$).

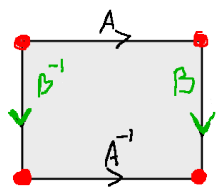
$$|E(G)| = 28 > 24 = 3|V(G)| + 3g - 6$$



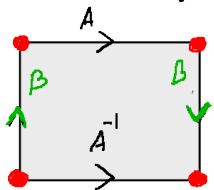
sphere, $g=0$



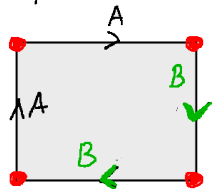
projective plane,
 $g=1$

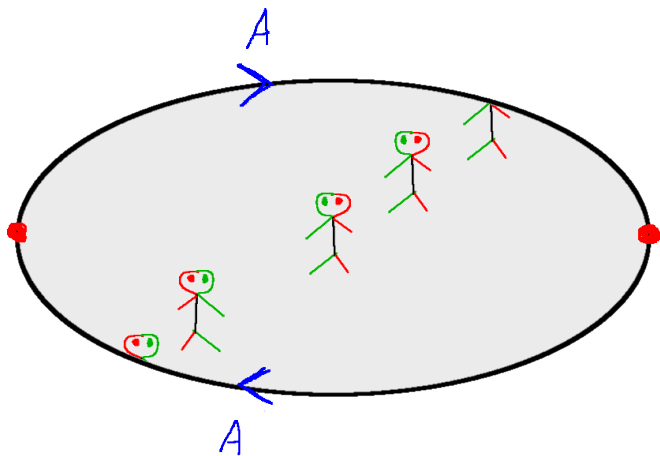


torus, $g=2$



Klein bottle, $g=2$



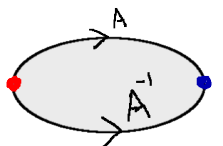


Definition

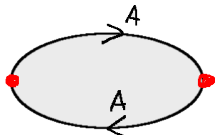
A surface is **orientable** if you can consistently define orientation at every point in the surface, and **non-orientable** otherwise.

Observation

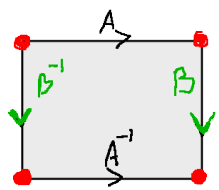
A surface is non-orientable if and only if it is represented by an expression of form Aw_1Aw_2 .



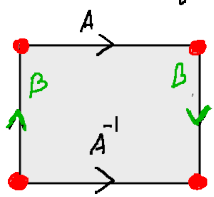
sphere, $g=0$



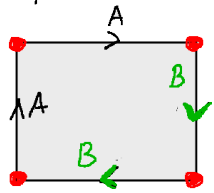
projective plane,
 $g=1$



torus, $g=2$



Klein bottle, $g=2$



Theorem (Classification theorem)

Every surface has a representation in one of the two following forms:

- $(ABA^{-1}B^{-1})(CDC^{-1}D^{-1})\dots$
 - *orientable, k blocks \rightarrow Euler genus $2k$*
- $(AA)(BB)(CC)\dots$
 - *non-orientable, k blocks \rightarrow Euler genus k*

Corollary

Two surfaces are homeomorphic if and only if they have the same Euler genus and orientability.

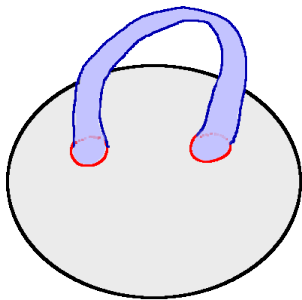
Corollary

The Euler genus of an orientable surface is always even.

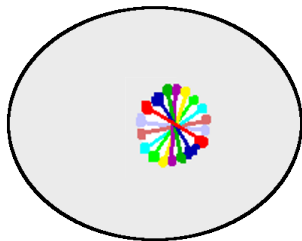
The **genus** of a surface Σ :

- Euler genus/2 if Σ is orientable.
- Euler genus if Σ is non-orientable.

Another approach: Start with a sphere, then add handles and crosscaps:



handle



Crosscap

Observation

A surface obtained from the sphere by adding a handles and b crosscaps has Euler genus $2a + b$, and it is orientable iff $b = 0$. Consequently, every surface is homeomorphic to some surface obtained in this way.