

Linear Algebra 1

Lecture #2

Matrix-vector equations. The rank of a matrix.
Matrix operations

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October 16, 2024

- This lecture covers sections 1.4-1.8 of the Lecture Notes (<https://iuuk.mff.cuni.cz/~ipenev/LALectureNotes.pdf>).

This lecture has six parts:

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- 1 Algebraic operations on vectors and linear span

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- 2 Matrix-vector multiplication
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- 4 The rank of a matrix
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- 6 The transpose of a matrix

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- For vectors $\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$ and $\mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$ in \mathbb{F}^n , we define

- $\mathbf{x} + \mathbf{y} := \begin{bmatrix} x_1 + y_1 \\ \vdots \\ x_n + y_n \end{bmatrix};$
- $\mathbf{x} - \mathbf{y} := \begin{bmatrix} x_1 - y_1 \\ \vdots \\ x_n - y_n \end{bmatrix}.$

1 Algebraic operations on vectors and linear span

- Let \mathbb{F} be a field.

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- $\mathbf{x} + \mathbf{y} := \begin{bmatrix} x_1 + y_1 \\ \vdots \\ x_n + y_n \end{bmatrix}$; $\mathbf{x} - \mathbf{y} := \begin{bmatrix} x_1 - y_1 \\ \vdots \\ x_n - y_n \end{bmatrix}$.

- For a vector $\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$ in \mathbb{F}^n and a scalar $\alpha \in \mathbb{F}$, we define

- $\alpha \mathbf{x} := \begin{bmatrix} \alpha x_1 \\ \vdots \\ \alpha x_n \end{bmatrix}$.

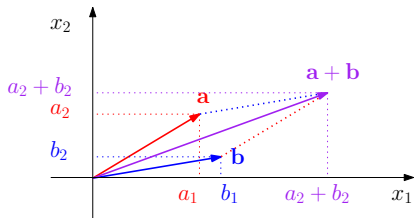
Example 1.4.1

Consider the vectors $\mathbf{x} = \begin{bmatrix} 0 \\ 1 \\ 2 \\ 2 \end{bmatrix}$ and $\mathbf{y} = \begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \end{bmatrix}$ in \mathbb{Z}_3^4 . Then

$$\bullet \mathbf{x} + \mathbf{y} = \begin{bmatrix} 0+1 \\ 1+0 \\ 2+2 \\ 2+1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}; \quad \bullet 2\mathbf{x} = \begin{bmatrix} 2 \cdot 0 \\ 2 \cdot 1 \\ 2 \cdot 2 \\ 2 \cdot 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 1 \\ 1 \end{bmatrix}.$$

- Vector addition and scalar multiplication in \mathbb{R}^2 have a nice geometric interpretation.

- To add two vectors in \mathbb{R}^2 , say $\mathbf{a} = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$, we apply the “parallelogram rule.”



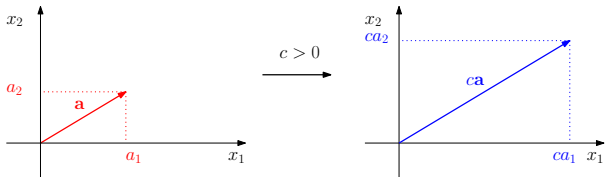
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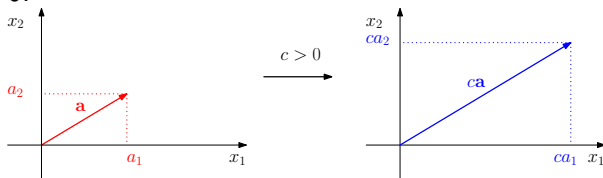
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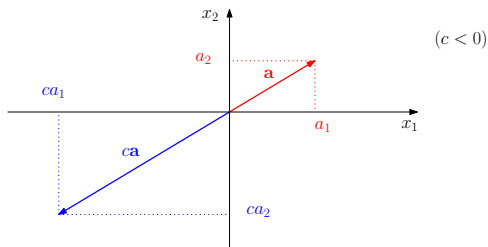
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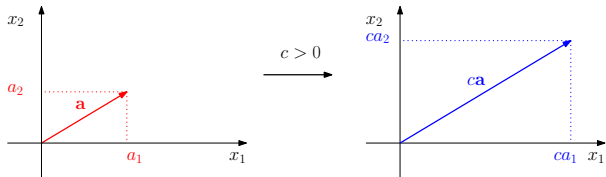
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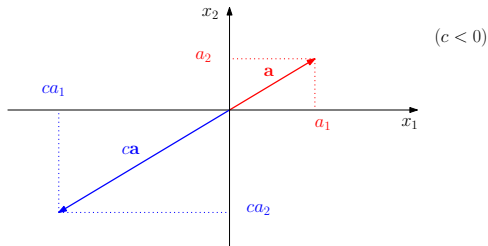
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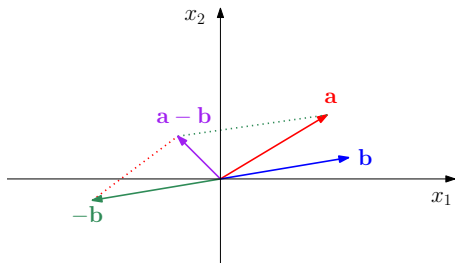
- If $c < 0$:



- If $c = 0$, then $c\mathbf{a} = \mathbf{0}$, which is simply the origin.

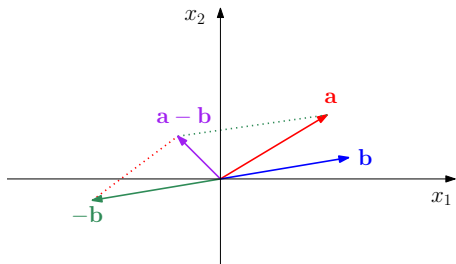
- For vectors $\mathbf{a} = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$ in \mathbb{R}^2 , we note that

$$\mathbf{a} - \mathbf{b} = \mathbf{a} + (-1)\mathbf{b}.$$



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- For vectors in \mathbb{R}^3 , we have a similar geometric interpretation of vector addition and scalar multiplication (and vector subtraction), only in the three-dimensional Euclidean space.

Definition

Suppose \mathbb{F} is some field. A *linear combination* of vectors $\mathbf{v}_1, \dots, \mathbf{v}_k$ in \mathbb{F}^n is any sum of the form

$$\sum_{i=1}^k \alpha_i \mathbf{v}_i = \alpha_1 \mathbf{v}_1 + \dots + \alpha_k \mathbf{v}_k,$$

where $\alpha_1, \dots, \alpha_k$ are scalars from the field \mathbb{F} .

- For example, in \mathbb{R}^3 , vectors $\begin{bmatrix} 5 \\ 6 \\ 5 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 3 \\ 0 \end{bmatrix}$, and $\begin{bmatrix} -3 \\ -9 \\ -3 \end{bmatrix}$ are linear combinations of the vectors $\begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ because

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- Similarly, $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ is a linear combination of the vector $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ in \mathbb{Z}_3^2 because $\begin{bmatrix} 2 \\ 1 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 2 \end{bmatrix}.$

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- We note that in \mathbb{F}^n (where \mathbb{F} is a field), the zero vector $\mathbf{0}$ is a linear combination of **any** vectors $\mathbf{v}_1, \dots, \mathbf{v}_k$ because

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- Moreover, we define the “empty sum” of vectors in \mathbb{F}^n (or the sum of an “empty list” of vectors in \mathbb{F}^n) to be $\mathbf{0}$, where $\mathbf{0}$ is the zero vector in \mathbb{F}^n .

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The *linear span* (or simply *span*) of vectors $\mathbf{v}_1, \dots, \mathbf{v}_k$ in \mathbb{F}^n (where \mathbb{F} is a field), denoted by $\text{Span}(\{\mathbf{v}_1, \dots, \mathbf{v}_k\})$ or simply $\text{Span}(\mathbf{v}_1, \dots, \mathbf{v}_k)$, is the set of all linear combinations of vectors $\mathbf{v}_1, \dots, \mathbf{v}_k$. In other words,

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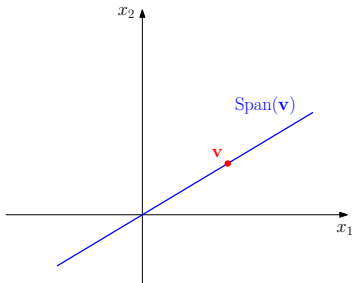
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- Obviously, $\text{Span}(\mathbf{0}) = \{\mathbf{0}\}$.

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- If $\mathbf{v} \neq \mathbf{0}$, then $\text{Span}(\mathbf{v}) = \{\alpha\mathbf{v} \mid \alpha \in \mathbb{R}\}$ is the line through the origin containing \mathbf{v} : indeed, $\text{Span}(\mathbf{v})$ is the set of all scalar multiples of \mathbf{v} , which is precisely the line through $\mathbf{0}$ and \mathbf{v} .



- What if we have two vectors \mathbf{v}_1 and \mathbf{v}_2 ?

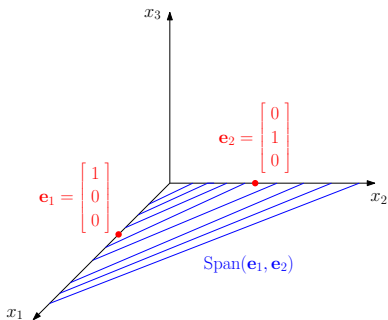
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- The case that is particularly easy to visualize is that of the

vectors $\mathbf{e}_1 := \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ and $\mathbf{e}_2 := \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ in \mathbb{R}^3 :

$$\begin{aligned} \text{Span}(\mathbf{e}_1, \mathbf{e}_2) &= \left\{ a_1 \mathbf{e}_1 + a_2 \mathbf{e}_2 \mid a_1, a_2 \in \mathbb{R} \right\} \\ &= \left\{ \begin{bmatrix} a_1 \\ a_2 \\ 0 \end{bmatrix} \mid a_1, a_2 \in \mathbb{R} \right\}, \end{aligned}$$

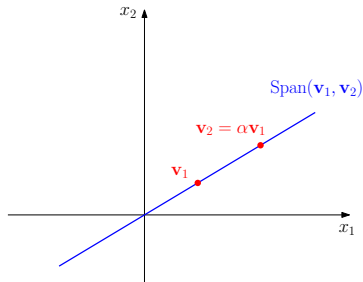
which is simply the x_1x_2 -plane in \mathbb{R}^3 (next slide).



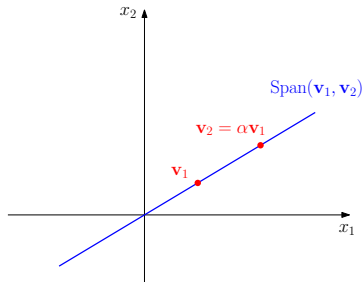
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- In general, for vectors $\mathbf{v}_1, \dots, \mathbf{v}_k$ in \mathbb{R}^n , the set $\text{Span}(\mathbf{v}_1, \dots, \mathbf{v}_k)$ is the smallest “flat” (point, line, plane, or higher dimensional generalization) containing the **origin** and all the vectors $\mathbf{v}_1, \dots, \mathbf{v}_k$.

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Definition

Suppose that \mathbb{F} is some field. Given a matrix $A \in \mathbb{F}^{n \times m}$ and a vector $\mathbf{x} \in \mathbb{F}^m$, say

$$A = \left[\mathbf{a}_1 \quad \dots \quad \mathbf{a}_m \right] \quad \text{and} \quad \mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix},$$

we define the *matrix-vector product* $A\mathbf{x}$ as follows:

$$A\mathbf{x} := \sum_{i=1}^m x_i \mathbf{a}_i = x_1 \mathbf{a}_1 + \dots + x_m \mathbf{a}_m.$$

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$$A\mathbf{x} := \sum_{i=1}^m x_i \mathbf{a}_i = x_1 \mathbf{a}_1 + \dots + x_m \mathbf{a}_m.$$

- Thus, $A\mathbf{x}$ is a linear combination of the columns of A , and the weights/scalars in front of the columns are determined by the entries of the vector \mathbf{x} .

- **Reminder:** For a matrix $A = \begin{bmatrix} \mathbf{a}_1 & \dots & \mathbf{a}_m \end{bmatrix} \in \mathbb{F}^{n \times m}$ and

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 - entries of the matrix A and entries of the vector \mathbf{x} must belong to the same field;
 - the number of **columns** of A must be the same as the number of **entries** of \mathbf{x} .
- Schematically, we have the following:

$$\underbrace{A}_{\in \mathbb{F}^{n \times m}} \underbrace{\mathbf{x}}_{\in \mathbb{F}^m} = \underbrace{A\mathbf{x}}_{\in \mathbb{F}^n}.$$

Example 1.4.2

Consider the matrix $A \in \mathbb{R}^{3 \times 2}$ and vector $\mathbf{x} \in \mathbb{R}^2$, given below:

$$A = \begin{bmatrix} -1 & 2 \\ 2 & 0 \\ 3 & -2 \end{bmatrix} \quad \text{and} \quad \mathbf{x} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}.$$

Then

$$\begin{aligned} \mathbf{Ax} &= \begin{bmatrix} -1 & 2 \\ 2 & 0 \\ 3 & -2 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} \\ &= 2 \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix} + 3 \begin{bmatrix} 2 \\ 0 \\ -2 \end{bmatrix} \\ &= \begin{bmatrix} 4 \\ 4 \\ 0 \end{bmatrix}. \end{aligned}$$

Example 1.4.3

Consider the matrix $A \in \mathbb{Z}_2^{2 \times 3}$ and vector $\mathbf{x} \in \mathbb{Z}_2^3$, given below:

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \quad \text{and} \quad \mathbf{x} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}.$$

Then

$$\begin{aligned} A\mathbf{x} &= \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \\ &= 1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 0 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ 1 \end{bmatrix}. \end{aligned}$$

Proposition 1.4.4

Let \mathbb{F} be a field, let $\mathbf{a}_1, \dots, \mathbf{a}_m \in \mathbb{F}^n$, and set $A := [\mathbf{a}_1 \ \dots \ \mathbf{a}_m]$.

Then

$$\text{Span}(\mathbf{a}_1, \dots, \mathbf{a}_m) = \{ \mathbf{A}\mathbf{x} \mid \mathbf{x} \in \mathbb{F}^m \}.$$

Proof.

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Proof. We compute:

$$\begin{aligned} \text{Span}(\mathbf{a}_1, \dots, \mathbf{a}_m) &= \{ x_1 \mathbf{a}_1 + \dots + x_m \mathbf{a}_m \mid x_1, \dots, x_m \in \mathbb{F} \} \\ &= \left\{ [\mathbf{a}_1 \ \dots \ \mathbf{a}_m] \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix} \mid x_1, \dots, x_m \in \mathbb{F} \right\} \\ &= \{ \mathbf{A}\mathbf{x} \mid \mathbf{x} \in \mathbb{F}^m \}. \end{aligned}$$

This completes the argument. \square

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- **Remark:** Suppose that $\mathbf{a}_1, \dots, \mathbf{a}_m \in \mathbb{F}^n$, where \mathbb{F} is some field, and set $A := [\mathbf{a}_1 \ \dots \ \mathbf{a}_m]$.

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 - Proposition 1.4.4 states that $\text{Span}(\mathbf{a}_1, \dots, \mathbf{a}_m)$, which we defined as the set of all linear combinations of the vectors $\mathbf{a}_1, \dots, \mathbf{a}_m$, is in fact the set of all possible matrix-vector products $A\mathbf{x}$.
 - Here, our matrix $A = [\mathbf{a}_1 \ \dots \ \mathbf{a}_m]$ is fixed, and the vector $\mathbf{x} \in \mathbb{F}^m$ is allowed to vary.

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 - Here, our matrix $A = [\mathbf{a}_1 \ \dots \ \mathbf{a}_m]$ is fixed, and the vector $\mathbf{x} \in \mathbb{F}^m$ is allowed to vary.
 - $\text{Span}(\mathbf{a}_1, \dots, \mathbf{a}_m)$, the span of the columns of A , has a special name: it is called the “column space” of the matrix A , and it is denoted by $\text{Col}(A)$.
 - To be studied later in the course.

- Let \mathbb{F} be a field. For each positive integer n and index $i \in \{1, \dots, n\}$, the vector \mathbf{e}_i^n is the vector in \mathbb{F}^n whose i -th entry is 1, and all of whose other entries are 0's.

$$\mathbf{e}_i^n = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \mathbf{1} \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad \leftarrow i\text{-th entry}$$

- When n is clear from context, we drop the superscript n , and we write $\mathbf{e}_1, \dots, \mathbf{e}_n$ instead of $\mathbf{e}_1^n, \dots, \mathbf{e}_n^n$, respectively.
- Vectors $\mathbf{e}_1, \dots, \mathbf{e}_n$ are called the *standard basis vectors* of \mathbb{F}^n , and the set $\mathcal{E}_n := \{\mathbf{e}_1, \dots, \mathbf{e}_n\}$ is called the *standard basis* of \mathbb{F}^n .

$$\mathbf{e}_i^n = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \mathbf{1} \\ 0 \\ \vdots \\ 0 \end{bmatrix} \leftarrow i\text{-th entry}$$

- We note that any vector $\mathbf{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}$ in \mathbb{F}^n can be expressed as a linear combination of the standard basis vectors $\mathbf{e}_1, \dots, \mathbf{e}_n$ in a unique way, namely

$$\mathbf{v} = v_1\mathbf{e}_1 + \cdots + v_n\mathbf{e}_n.$$

Proposition 1.4.5

Let \mathbb{F} be a field, and let $A = \begin{bmatrix} \mathbf{a}_1 & \dots & \mathbf{a}_m \end{bmatrix}$ be a matrix in $\mathbb{F}^{n \times m}$. Then for all indices $i \in \{1, \dots, m\}$, we have that $A\mathbf{e}_i^m = \mathbf{a}_i$.

- **Remark:** Proposition 1.4.4 states that multiplying a matrix by the i -th standard basis vector yields the i -th column of the matrix that we started with.

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Proof. Fix $i \in \{1, \dots, m\}$. Then

$$\begin{aligned} A\mathbf{e}_i^m &= \begin{bmatrix} \mathbf{a}_1 & \dots & \mathbf{a}_{i-1} & \mathbf{a}_i & \mathbf{a}_{i+1} & \dots & \mathbf{a}_m \end{bmatrix} \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \mathbf{1} \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad \leftarrow i\text{-th entry} \\ &= 0\mathbf{a}_1 + \dots + 0\mathbf{a}_{i-1} + \mathbf{1}\mathbf{a}_i + 0\mathbf{a}_{i+1} + \dots + 0\mathbf{a}_m = \mathbf{a}_i, \end{aligned}$$

which is what we needed to show. \square

- For a field \mathbb{F} , the *identity matrix* in $\mathbb{F}^{n \times n}$ is the $n \times n$ matrix

$$I_n := \begin{bmatrix} \mathbf{e}_1^n & \cdots & \mathbf{e}_n^n \end{bmatrix}.$$

- For a field \mathbb{F} , the *identity matrix* in $\mathbb{F}^{n \times n}$ is the $n \times n$ matrix

$$I_n := \begin{bmatrix} \mathbf{e}_1^n & \dots & \mathbf{e}_n^n \end{bmatrix}.$$

- In other words, the identity matrix I_n is the $n \times n$ matrix with 1's on the main diagonal and 0's elsewhere (where the 1's and the 0's are from the field \mathbb{F}). Schematically, we have that

$$I_n = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 & 0 \\ 0 & 1 & 0 & \dots & 0 & 0 \\ 0 & 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 1 & 0 \\ 0 & 0 & 0 & \dots & 0 & 1 \end{bmatrix}_{n \times n}$$

for all positive integers n .

Proposition 1.4.6

Let \mathbb{F} be a field. Then for all vectors $\mathbf{v} \in \mathbb{F}^n$, we have that $I_n \mathbf{v} = \mathbf{v}$.

- **Remark:** Proposition 1.4.5 states that if we multiply the identity matrix by a vector, we obtain that same vector.

For any vector $\mathbf{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}$ in \mathbb{F}^n , we have that (next slide):

$$I_n \mathbf{v} = \begin{bmatrix} \mathbf{e}_1^n & \mathbf{e}_2^n & \cdots & \mathbf{e}_n^n \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

$$= v_1 \mathbf{e}_1^n + v_2 \mathbf{e}_2^n + \cdots + v_n \mathbf{e}_n^n$$

$$= v_1 \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + v_2 \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix} + \cdots + v_n \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \mathbf{v}.$$

□

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Let \mathbb{F} be a field, and let $A = \begin{bmatrix} \mathbf{a}_1 & \dots & \mathbf{a}_m \end{bmatrix}$ be a matrix in $\mathbb{F}^{n \times m}$. Then for all indices $i \in \{1, \dots, m\}$, we have that $A\mathbf{e}_i^m = \mathbf{a}_i$.

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Proposition 1.4.6

Let \mathbb{F} be a field. Then both the following hold:

- Ⓐ for all $\mathbf{v} \in \mathbb{F}^m$, we have that $O_{n \times m} \mathbf{v} = \mathbf{0}$;^a
- Ⓑ for all matrices $A \in \mathbb{F}^{n \times m}$, we have that $A\mathbf{0} = \mathbf{0}$.^b

^aHere, the zero vector $\mathbf{0}$ belongs to \mathbb{F}^n .

^bIn the expression $A\mathbf{0} = \mathbf{0}$, we have that $\mathbf{0} \in \mathbb{F}^m$ and $\mathbf{0} \in \mathbb{F}^n$.

Proof. This readily follows from the definition of matrix-vector multiplication.

3 Matrix-vector equations

- A *matrix-vector equation* is an equation of the form

$$A\mathbf{x} = \mathbf{b},$$

where the matrix A and vector \mathbf{b} are known, and the vector \mathbf{x} is unknown.

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- A matrix-vector equation $A\mathbf{x} = \mathbf{b}$ is equivalent to a system of linear equations whose augmented matrix is $\left[A \mid \mathbf{b} \right]$.
 - Details: next slide.
 - The matrix $\left[A \mid \mathbf{b} \right]$ will also be referred to as the *augmented matrix* of the matrix-vector equation $A\mathbf{x} = \mathbf{b}$.

$$Ax = \mathbf{b} \iff \underbrace{\begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,m} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n,1} & a_{n,2} & \cdots & a_{n,m} \end{bmatrix}}_{=A} \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix}}_{=x} = \underbrace{\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}}_{=b}$$

$$\iff x_1 \begin{bmatrix} a_{1,1} \\ a_{2,1} \\ \vdots \\ a_{n,1} \end{bmatrix} + x_2 \begin{bmatrix} a_{1,2} \\ a_{2,2} \\ \vdots \\ a_{n,2} \end{bmatrix} + \cdots + x_m \begin{bmatrix} a_{1,m} \\ a_{2,m} \\ \vdots \\ a_{n,m} \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$\iff \begin{bmatrix} a_{1,1}x_1 + a_{1,2}x_2 + \cdots + a_{1,m}x_m \\ a_{2,1}x_1 + a_{2,2}x_2 + \cdots + a_{2,m}x_m \\ \vdots \\ a_{n,1}x_1 + a_{n,2}x_2 + \cdots + a_{n,m}x_m \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$\iff \begin{cases} a_{1,1}x_1 + a_{1,2}x_2 + \cdots + a_{1,m}x_m = b_1 \\ a_{2,1}x_1 + a_{2,2}x_2 + \cdots + a_{2,m}x_m = b_2 \\ \vdots \\ a_{n,1}x_1 + a_{n,2}x_2 + \cdots + a_{n,m}x_m = b_n \end{cases}$$

Example 1.5.1

Solve the matrix-vector equation $A\mathbf{x} = \mathbf{b}$, where

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix} \quad \text{and} \quad \mathbf{b} = \begin{bmatrix} 2 \\ 6 \end{bmatrix},$$

with entries understood to be in \mathbb{R} . How many solutions does the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ have?

Solution.

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Solution. The augmented matrix of $A\mathbf{x} = \mathbf{b}$ is

$$\left[A \mid \mathbf{b} \right] = \left[\begin{array}{cc|c} 1 & 2 & 2 \\ 3 & 6 & 6 \end{array} \right].$$

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$$\left[A \mid \mathbf{b} \right] = \left[\begin{array}{cc|c} 1 & 2 & 2 \\ 3 & 6 & 6 \end{array} \right].$$

We now row reduce in order to find $\text{RREF}\left(\left[A \mid \mathbf{b} \right]\right)$, as follows:

$$\left[A \mid \mathbf{b} \right] = \left[\begin{array}{cc|c} 1 & 2 & 2 \\ 3 & 6 & 6 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - 3R_1} \left[\begin{array}{cc|c} 1 & 2 & 2 \\ 0 & 0 & 0 \end{array} \right].$$

Solution (continued). The last matrix from the computation above is in reduced row echelon form, and we deduce that

$$\text{RREF}\left(\left[\begin{array}{cc|c} A & \mathbf{b} \end{array} \right]\right) = \left[\begin{array}{cc|c} 1 & 2 & 2 \\ 0 & 0 & 0 \end{array} \right].$$

Solution (continued). The last matrix from the computation above is in reduced row echelon form, and we deduce that

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The matrix $\text{RREF}\left(\left[A \mid \mathbf{b} \right]\right)$ is the augmented matrix of the linear system below.

$$\begin{array}{rcl} x_1 & + & 2x_2 = 2 \\ & & 0 = 0 \end{array}$$

Solution (continued). The last matrix from the computation above is in reduced row echelon form, and we deduce that

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$$\begin{array}{rcl} x_1 & + & 2x_2 = 2 \\ & & 0 = 0 \end{array}$$

The system is consistent, with one free variable (namely, x_2). We read off the solutions as follows.

$$\begin{array}{l} x_1 = -2s + 2 \\ x_2 = s, \end{array} \quad \text{where } s \in \mathbb{R}.$$

Solution (continued). So, the general solution of the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ is

$$\mathbf{x} = \begin{bmatrix} -2s + 2 \\ s \end{bmatrix}, \quad \text{where } s \in \mathbb{R}.$$

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Here is another way to write the general solution of the matrix-vector equation $A\mathbf{x} = \mathbf{b}$:

$$\mathbf{x} = \begin{bmatrix} 2 \\ 0 \end{bmatrix} + s \begin{bmatrix} -2 \\ 1 \end{bmatrix}, \quad \text{where } s \in \mathbb{R}.$$

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The set of solutions of the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ is

$$\left\{ \begin{bmatrix} -2s + 2 \\ s \end{bmatrix} \mid s \in \mathbb{R} \right\} = \left\{ \begin{bmatrix} 2 \\ 0 \end{bmatrix} + s \begin{bmatrix} -2 \\ 1 \end{bmatrix} \mid s \in \mathbb{R} \right\}.$$

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Since the parameter s can take infinitely many values (because \mathbb{R} is infinite), the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ has infinitely many solutions. \square

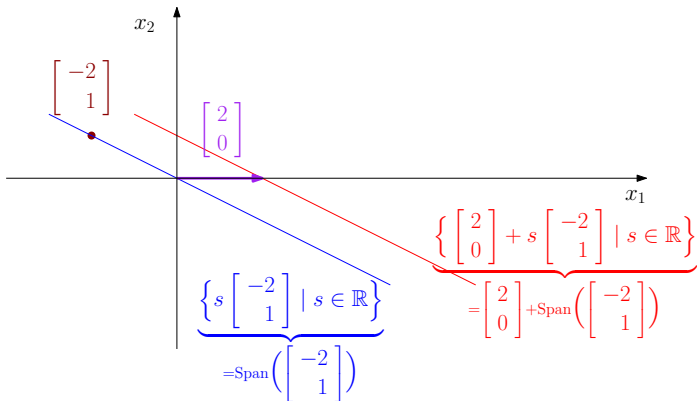
- **Reminder:** The solution set is

$$\left\{ \begin{bmatrix} -2s+2 \\ s \end{bmatrix} \mid s \in \mathbb{R} \right\} = \left\{ \begin{bmatrix} 2 \\ 0 \end{bmatrix} + s \begin{bmatrix} -2 \\ 1 \end{bmatrix} \mid s \in \mathbb{R} \right\}.$$

- **Reminder:** The solution set is

$$\left\{ \begin{bmatrix} -2s+2 \\ s \end{bmatrix} \mid s \in \mathbb{R} \right\} = \left\{ \begin{bmatrix} 2 \\ 0 \end{bmatrix} + s \begin{bmatrix} -2 \\ 1 \end{bmatrix} \mid s \in \mathbb{R} \right\}.$$

- This solution set has a geometric interpretation:



Example 1.5.2

Solve the matrix-vector equation $A\mathbf{x} = \mathbf{b}$, where

$$A = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 2 & 2 & 1 & 1 \end{bmatrix} \quad \text{and} \quad \mathbf{b} = \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix},$$

with entries understood to be in \mathbb{Z}_3 . How many solutions does the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ have?

Solution.

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with entries understood to be in \mathbb{Z}_3 . How many solutions does the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ have?

Solution. The augmented matrix of the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ is

$$\left[A \mid \mathbf{b} \right] = \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 2 \\ 1 & 0 & 1 & 0 & 2 \\ 2 & 2 & 1 & 1 & 0 \end{array} \right].$$

Example 1.5.2

Solve the matrix-vector equation $A\mathbf{x} = \mathbf{b}$, where

$$A = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 2 & 2 & 1 & 1 \end{bmatrix} \quad \text{and} \quad \mathbf{b} = \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix},$$

with entries understood to be in \mathbb{Z}_3 . How many solutions does the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ have?

Solution. The augmented matrix of the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ is

$$\left[A \mid \mathbf{b} \right] = \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 2 \\ 1 & 0 & 1 & 0 & 2 \\ 2 & 2 & 1 & 1 & 0 \end{array} \right].$$

We now row reduce in order to find $\text{RREF}\left(\left[A \mid \mathbf{b} \right]\right)$, as follows (next slide):

Solution (continued).

$$\left[\begin{array}{ccc|c} \mathbf{A} & & & \mathbf{b} \end{array} \right] = \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 2 \\ 1 & 0 & 1 & 0 & 2 \\ 2 & 2 & 1 & 1 & 0 \end{array} \right]$$

$$\begin{array}{l} R_2 \rightarrow R_2 + 2R_1 \\ R_3 \rightarrow R_3 + R_1 \\ \sim \end{array} \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 2 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 1 & 1 & 2 & 2 \end{array} \right]$$

$$R_3 \rightarrow R_3 + 2R_2 \\ \sim \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 2 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{array} \right]$$

$$R_3 \rightarrow 2R_3 \\ \sim \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 2 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{array} \right]$$

$$R_1 \rightarrow R_1 + R_3 \\ \sim \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 0 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{array} \right]$$

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Solution (continued). The last matrix from the computation above is in reduced row echelon form, and we deduce that

$$\text{RREF}\left(\left[A \mid \mathbf{b} \right]\right) = \left[\begin{array}{cccc|c} 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{array} \right].$$

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We see from $\text{RREF}\left(\left[A \mid \mathbf{b} \right]\right)$ that the rightmost column of $\left[A \mid \mathbf{b} \right]$ is a pivot column; consequently, the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ is inconsistent, i.e. the solution set of the equation $A\mathbf{x} = \mathbf{b}$ is \emptyset . (The number of solutions of the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ is zero.) \square

Solution (continued). The last matrix from the computation above is in reduced row echelon form, and we deduce that

$$\text{RREF}\left(\left[A \mid \mathbf{b} \right]\right) = \left[\begin{array}{cccc|c} 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{array} \right].$$

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- Here is the row reduction again (next slide):

$$\left[A \mid \mathbf{b} \right] = \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 2 \\ 1 & 0 & 1 & 0 & 2 \\ 2 & 2 & 1 & 1 & 0 \end{array} \right]$$

$$\begin{array}{l} R_2 \rightarrow R_2 + 2R_1 \\ R_3 \rightarrow R_3 + R_1 \\ \sim \end{array} \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 2 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 1 & 1 & 2 & 2 \end{array} \right]$$

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$$\left[A \mid \mathbf{b} \right] \sim \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 2 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{array} \right]$$

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- We could in fact have stopped as soon as we got the red matrix (despite the fact that this matrix is not in reduced row echelon form).

$$\left[A \mid \mathbf{b} \right] \sim \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 2 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{array} \right]$$

- We could in fact have stopped as soon as we got the **red** matrix (despite the fact that this matrix is not in reduced row echelon form).
- This is because the bottom row of the **red** matrix encodes the equation $0 = 2$, which has no solutions.

$$\left[A \mid \mathbf{b} \right] \sim \left[\begin{array}{cccc|c} 1 & 2 & 0 & 1 & 2 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{array} \right]$$

- We could in fact have stopped as soon as we got the **red** matrix (despite the fact that this matrix is not in reduced row echelon form).
- This is because the bottom row of the **red** matrix encodes the equation $0 = 2$, which has no solutions.
- Indeed, as soon as we obtain a row of the form $\left[0 \ \dots \ 0 \mid \blacksquare \right]$, where \blacksquare is a non-zero number, we can stop row reducing, and we can deduce that the system has no solutions (because this row encodes the equation $0 = \blacksquare$, and \blacksquare is non-zero).

Example 1.6.1

Find the rank of each of the following matrices.

a) $A = \begin{bmatrix} 0 & -3 & -6 & 3 & 4 & -1 \\ 2 & 1 & -4 & 13 & -4 & 3 \\ 2 & 3 & 0 & 11 & -6 & 5 \end{bmatrix}$, with entries understood to be in \mathbb{R} ;

b) $B = \begin{bmatrix} 0 & 1 & 1 & 0 & 2 \\ 2 & 1 & 0 & 1 & 1 \\ 2 & 1 & 1 & 1 & 1 \\ 1 & 0 & 2 & 2 & 1 \end{bmatrix}$, with entries understood to be in \mathbb{Z}_3 .

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$$\text{RREF}(A) = \begin{bmatrix} 1 & 0 & -3 & 7 & 0 & 4 \\ 0 & 1 & 2 & -1 & 0 & 3 \\ 0 & 0 & 0 & 0 & 1 & 2 \end{bmatrix}.$$

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The matrix $\text{RREF}(A)$ has three pivot columns (equivalently: three pivot positions or three non-zero rows), and so $\text{rank}(A) = 3$. \square

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Solution#2.

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$$\begin{bmatrix} 2 & 3 & 0 & 11 & -6 & 5 \\ 0 & -2 & -4 & 2 & 2 & -2 \\ 0 & 0 & 0 & 0 & 1 & 2 \end{bmatrix}.$$

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This row echelon matrix has three pivot columns (equivalently: three pivot positions or three non-zero rows), and so $\text{rank}(A) = 3$. \square

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Find the rank of each of the following matrices.

b) $B = \begin{bmatrix} 0 & 1 & 1 & 0 & 2 \\ 2 & 1 & 0 & 1 & 1 \\ 2 & 1 & 1 & 1 & 1 \\ 1 & 0 & 2 & 2 & 1 \end{bmatrix}$, with entries understood to be in \mathbb{Z}_3 .

Solution#1.

Example 1.6.1

Find the rank of each of the following matrices.

$$\textcircled{b} \quad B = \begin{bmatrix} 0 & 1 & 1 & 0 & 2 \\ 2 & 1 & 0 & 1 & 1 \\ 2 & 1 & 1 & 1 & 1 \\ 1 & 0 & 2 & 2 & 1 \end{bmatrix}, \text{ with entries understood to be in } \mathbb{Z}_3.$$

Solution#1. (b) In Example 1.3.10, we computed

$$\text{RREF}(B) = \begin{bmatrix} 1 & 0 & 0 & 2 & 1 \\ 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

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Find the rank of each of the following matrices.

$$\textcircled{b} \quad B = \begin{bmatrix} 0 & 1 & 1 & 0 & 2 \\ 2 & 1 & 0 & 1 & 1 \\ 2 & 1 & 1 & 1 & 1 \\ 1 & 0 & 2 & 2 & 1 \end{bmatrix}, \text{ with entries understood to be in } \mathbb{Z}_3.$$

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The matrix $\text{RREF}(B)$ has three pivot columns (equivalently: three pivot positions or three non-zero rows), and so $\text{rank}(B) = 3$. \square

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Find the rank of each of the following matrices.

b) $B = \begin{bmatrix} 0 & 1 & 1 & 0 & 2 \\ 2 & 1 & 0 & 1 & 1 \\ 2 & 1 & 1 & 1 & 1 \\ 1 & 0 & 2 & 2 & 1 \end{bmatrix}$, with entries understood to be in \mathbb{Z}_3 .

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Solution#2. (b) In Example 1.3.10, we saw that the matrix B is row equivalent to the following matrix in row echelon form:

$$\begin{bmatrix} 1 & 0 & 2 & 2 & 1 \\ 0 & 1 & 2 & 0 & 2 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

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Corollary 1.3.8

Two matrices (with entries in some field) are row equivalent iff they have the same reduced row echelon form.

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Proposition 1.6.2

Row equivalent matrices (with entries in some field) have the same rank.

Proof (outline).

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Proof (outline). By Corollary 1.3.8, row equivalent matrices have the same RREF.

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Proposition 1.6.2

Row equivalent matrices (with entries in some field) have the same rank.

Proof (outline). By Corollary 1.3.8, row equivalent matrices have the same RREF. By definition, the rank of a matrix can be read off from its RREF (it is simply the number of non-zero rows of the RREF). \square

$$\begin{bmatrix} 0 & \blacksquare & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & \blacksquare & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \blacksquare & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Proposition 1.6.3

Let A be an $n \times m$ matrix (with entries in some field \mathbb{F}). Then $\text{rank}(A) \leq \min\{n, m\}$.^a

^aThis means that $\text{rank}(A) \leq n$ (i.e. $\text{rank}(A)$ is at most the number of rows of A) and $\text{rank}(A) \leq m$ (i.e. $\text{rank}(A)$ is at most the number of columns of A).

- Proof: Follows immediately from the definition of rank. (The full details are in the lecture notes.)

$$\begin{bmatrix} 0 & \blacksquare & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & \blacksquare & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \blacksquare & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

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Let \mathbb{F} be a field, and let A be an $n \times m$ matrix (with entries in some field \mathbb{F}). Then $\text{rank}(A) \leq \min\{n, m\}$.^a

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$$\begin{bmatrix} 0 & \blacksquare & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & \blacksquare & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \blacksquare & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

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 - if $\text{rank}(A) = \min\{n, m\}$, then A is said to have *full rank*;
 - if $\text{rank}(A) < \min\{n, m\}$, then A is said to be *rank-deficient*.

- As Theorem 1.6.4 (next slide) shows, the number of solutions of a matrix-vector equation $A\mathbf{x} = \mathbf{b}$ can easily be determined if we know the size of the matrix A (i.e. the number of rows and columns of A) and we also know $\text{rank}(A)$ and $\text{rank}\left(\begin{bmatrix} A & \mathbf{b} \end{bmatrix}\right)$.
 - The detailed proof of Theorem 1.6.4 is in the Lecture Notes.
 - An outline of the proof: on the board!

Theorem 1.6.4

Let \mathbb{F} be a field, and let $A \in \mathbb{F}^{n \times m}$ and $\mathbf{b} \in \mathbb{F}^n$. Then

$$\text{rank}(A) \leq \text{rank}\left(\begin{bmatrix} A & \mathbf{b} \end{bmatrix}\right) \leq \text{rank}(A) + 1.$$

Moreover, all the following hold:

- (a) if $\text{rank}\left(\begin{bmatrix} A & \mathbf{b} \end{bmatrix}\right) \neq \text{rank}(A)$ (and consequently, $\text{rank}\left(\begin{bmatrix} A & \mathbf{b} \end{bmatrix}\right) = \text{rank}(A) + 1$), then $A\mathbf{x} = \mathbf{b}$ is inconsistent.
- (b) if $\text{rank}\left(\begin{bmatrix} A & \mathbf{b} \end{bmatrix}\right) = \text{rank}(A) = m$, then $A\mathbf{x} = \mathbf{b}$ has a unique solution.
- (c) if $\text{rank}\left(\begin{bmatrix} A & \mathbf{b} \end{bmatrix}\right) = \text{rank}(A) < m$, then $A\mathbf{x} = \mathbf{b}$ has more than one solution, and more precisely,
 - (c.1) if the field \mathbb{F} is finite, then $A\mathbf{x} = \mathbf{b}$ has exactly $|\mathbb{F}|^{m-\text{rank}(A)}$ many solutions,
 - (c.2) if the field \mathbb{F} is infinite, then $A\mathbf{x} = \mathbf{b}$ has infinitely many solutions.

Proposition 1.6.3

Let \mathbb{F} be a field, and let A be an $n \times m$ matrix (with entries in some field \mathbb{F}). Then $\text{rank}(A) \leq \min\{n, m\}$.

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 - if $\text{rank}(A) = \min\{n, m\}$, then A is said to have *full rank*;
 - if $\text{rank}(A) < \min\{n, m\}$, then A is said to be *rank-deficient*.
- Our next goal is to prove a couple of corollaries of Theorem 1.6.4 for matrices of full rank.

Proposition 1.6.3

Let \mathbb{F} be a field, and let A be an $n \times m$ matrix (with entries in some field \mathbb{F}). Then $\text{rank}(A) \leq \min\{n, m\}$.

- **Terminology:** For a field \mathbb{F} and a matrix $A \in \mathbb{F}^{n \times m}$ (so, A has n rows and m columns):
 - if $\text{rank}(A) = n$, then A is said to have *full row rank*;
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 - if $\text{rank}(A) = \min\{n, m\}$, then A is said to have *full rank*;
 - if $\text{rank}(A) < \min\{n, m\}$, then A is said to be *rank-deficient*.
- Our next goal is to prove and derive a couple of corollaries of Theorem 1.6.4 for matrices of full rank.
- By definition, a matrix of full rank has full column rank or full row rank (possibly both). We deal with these two cases separately.

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- Our next goal is to prove and derive a couple of corollaries of Theorem 1.6.4 for matrices of full rank.
- By definition, a matrix of full rank has full column rank or full row rank (possibly both). We deal with these two cases separately.
- After that, we prove Theorem 1.6.8, which deals with **square** matrices of full rank.
 - Note that such matrices have both full column rank and full row rank.

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- So, the reduced row echelon form of such a matrix is of the form

$$\begin{array}{c}
 \left[\begin{array}{cccccc}
 1 & 0 & 0 & \dots & 0 & 0 \\
 0 & 1 & 0 & \dots & 0 & 0 \\
 0 & 0 & 1 & \dots & 0 & 0 \\
 \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
 0 & 0 & 0 & \dots & 1 & 0 \\
 0 & 0 & 0 & \dots & 0 & 1 \\
 \hline
 0 & 0 & 0 & \dots & 0 & 0 \\
 0 & 0 & 0 & \dots & 0 & 0 \\
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- In a matrix of full column rank, all columns are pivot columns.
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- More precisely, if we have an $n \times m$ matrix of full column rank, then the reduced row echelon form of that matrix is obtained from the identity matrix I_m by adding $n - m$ many zero rows to the bottom.

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Corollary 1.6.5

Let \mathbb{F} be a field, and let $A \in \mathbb{F}^{n \times m}$. Then the following are equivalent:

- (a) $\text{rank}(A) = m$ (i.e. A has full column rank);
- (b) the homogeneous matrix-vector equation $A\mathbf{x} = \mathbf{0}$ has only the trivial solution (i.e. the solution $\mathbf{x} = \mathbf{0}$);
- (c) there exists some vector $\mathbf{b} \in \mathbb{F}^n$ s.t. the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ has a unique solution;
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The implications “(d) \implies (b)” and “(b) \implies (c)” are obvious, and “(c) \implies (a)” and “(a) \implies (d)” follow from Theorem 1.6.4.” \square

- We now consider matrices of full row rank.

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- Note that matrices of full row rank are precisely those matrices whose reduced row echelon form has no zero rows.

$$\begin{bmatrix} 0 & \blacksquare & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & \blacksquare & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \blacksquare & * & * \end{bmatrix} \quad \begin{bmatrix} 0 & 1 & * & 0 & 0 & * & * & 0 & * & * \\ 0 & 0 & 0 & 1 & 0 & * & * & 0 & * & * \\ 0 & 0 & 0 & 0 & 1 & * & * & 0 & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & * & * \end{bmatrix}$$

Corollary 1.6.6

Let \mathbb{F} be a field, and let $A \in \mathbb{F}^{n \times m}$. Then the following are equivalent:

- (a) $\text{rank}(A) = n$ (i.e. A has full row rank);
- (b) for all vectors $\mathbf{b} \in \mathbb{F}^n$, the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ is consistent.

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Let \mathbb{F} be a field, and let $A \in \mathbb{F}^{n \times m}$. Then the following are equivalent:

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$$\begin{aligned}n &= \text{rank}(A) && \text{by (a)} \\ &\leq \text{rank}\left(\begin{bmatrix} A \\ \mathbf{b} \end{bmatrix}\right) && \text{by Theorem 1.6.4} \\ &\leq n && \text{by Proposition 1.6.3,}\end{aligned}$$

and it follows that $\text{rank}\left(\begin{bmatrix} A \\ \mathbf{b} \end{bmatrix}\right) = \text{rank}(A) = n$. But now Theorem 1.6.4 guarantees that the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ is consistent. Thus, (b) holds.

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Proof (continued). Now, we perform the elementary row operations R'_k, \dots, R'_1 on the matrix $\left[\begin{array}{c} U \\ \mathbf{e}_{r+1} \end{array} \right]$, and we obtain the matrix $\left[\begin{array}{c} A \\ \mathbf{b} \end{array} \right]$ for some vector $\mathbf{b} \in \mathbb{F}^n$.

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Proposition 1.6.7

Let \mathbb{F} be a field. Then for all square matrices $A \in \mathbb{F}^{n \times n}$, we have that $\text{rank}(A) = n$ iff $\text{RREF}(A) = I_n$. In particular, $\text{rank}(I_n) = n$.

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Proof. I_n is a matrix in reduced row echelon form, and it has n pivot columns; so, $\text{rank}(I_n) = n$. Moreover, it is clear that I_n is the **only** reduced row echelon form matrix in $\mathbb{F}^{n \times n}$ of rank n .

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Now, fix any matrix $A \in \mathbb{F}^{n \times n}$. By Proposition 1.6.2, we have that $\text{rank}(A) = \text{rank}(\text{RREF}(A))$. Since I_n is the only reduced row echelon form matrix in $\mathbb{F}^{n \times n}$ of rank n , it follows that $\text{rank}(A) = n$ iff $\text{RREF}(A) = I_n$. \square

Theorem 1.6.8

Let \mathbb{F} be a field, and let $A \in \mathbb{F}^{n \times n}$ be a **square** matrix. Then the following are equivalent:

- (a) $\text{rank}(A) = n$ (i.e. the square matrix A has full rank);
- (b) $\text{RREF}(A) = I_n$;
- (c) the homogeneous matrix-vector equation $A\mathbf{x} = \mathbf{0}$ has only the trivial solution (i.e. the solution $\mathbf{x} = \mathbf{0}$);
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- (e) for all vectors $\mathbf{b} \in \mathbb{F}^n$, the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ has a unique solution;
- (f) for all vectors $\mathbf{b} \in \mathbb{F}^n$, the matrix-vector $A\mathbf{x} = \mathbf{b}$ equation has at most one solution;
- (g) for all vectors $\mathbf{b} \in \mathbb{F}^n$, the matrix-vector equation $A\mathbf{x} = \mathbf{b}$ is consistent.

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- Given matrices $A = [a_{i,j}]_{n \times m}$ and $B = [b_{i,j}]_{n \times m}$ in $\mathbb{F}^{n \times m}$, and given a scalar c , we define
 - $A + B := [a_{i,j} + b_{i,j}]_{n \times m}$;
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 - $cA := [ca_{i,j}]$.
- Thus, we add (resp. subtract) matrices by adding (resp. subtracting) corresponding entries, i.e.
 - $[a_{i,j}]_{n \times m} + [b_{i,j}]_{n \times m} = [a_{i,j} + b_{i,j}]_{n \times m}$;
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 - $[a_{i,j}]_{n \times m} - [b_{i,j}]_{n \times m} = [a_{i,j} - b_{i,j}]_{n \times m}$.
- Similarly, we multiply a matrix by a scalar (on the left) by multiplying each entry of the matrix by that scalar, i.e.
 - $c [a_{i,j}]_{n \times m} = [ca_{i,j}]_{n \times m}$.

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- Let \mathbb{F} be a field, and suppose that we are given two matrices, $A \in \mathbb{F}^{n \times m}$ and $B \in \mathbb{F}^{m \times p}$, where $B = \begin{bmatrix} \mathbf{b}_1 & \dots & \mathbf{b}_p \end{bmatrix}$.

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- Note that, for the product AB to be defined, the number of **columns** of A must be the same as the number of **rows** of B .

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$$AB := \begin{bmatrix} A\mathbf{b}_1 & \dots & A\mathbf{b}_p \end{bmatrix}$$

Note that $AB \in \mathbb{F}^{n \times p}$.

- Note that, for the product AB to be defined, the number of **columns** of A must be the same as the number of **rows** of B .
- The matrix AB has the same number of **rows** as A , and the same number of **columns** as B .

- We can also multiply matrices!
- Let \mathbb{F} be a field, and suppose that we are given two matrices, $A \in \mathbb{F}^{n \times m}$ and $B \in \mathbb{F}^{m \times p}$, where $B = \begin{bmatrix} \mathbf{b}_1 & \dots & \mathbf{b}_p \end{bmatrix}$.

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- The matrix AB has the same number of **rows** as A , and the same number of **columns** as B .
- Schematically, we get:

$$(n \times m) \cdot (m \times p) = (n \times p).$$

Example 1.7.1

Let

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & -3 & 1 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 1 \\ -2 & 1 \\ 0 & -1 \end{bmatrix},$$

with entries understood to be in \mathbb{R} . Compute AB .

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$$\mathbf{b}_1 = \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} \quad \text{and} \quad \mathbf{b}_2 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix},$$

$$\text{so that } B = \begin{bmatrix} \mathbf{b}_1 & \mathbf{b}_2 \end{bmatrix}.$$

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so that $B = \begin{bmatrix} \mathbf{b}_1 & \mathbf{b}_2 \end{bmatrix}$. Then $AB = \begin{bmatrix} A\mathbf{b}_1 & A\mathbf{b}_2 \end{bmatrix}$. We

compute $A\mathbf{b}_1 = \begin{bmatrix} -3 \\ 6 \end{bmatrix}$ and $A\mathbf{b}_2 = \begin{bmatrix} 4 \\ -4 \end{bmatrix}$, which yields

$$AB = \begin{bmatrix} -3 & 4 \\ 6 & -4 \end{bmatrix}. \quad \square$$

Proposition 1.7.2

Let \mathbb{F} be a field, let m, n, p be positive integers, and let $A \in \mathbb{F}^{n \times m}$ be a matrix. Then all the following hold:

- (a) $I_n A = A I_m = A$;
- (b) $A O_{m \times p} = O_{n \times p}$;
- (c) $O_{p \times n} A = O_{p \times m}$.

Proof.

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Proof. Parts (b) and (c) readily follow from the appropriate definitions (the details are left as an easy exercise). Let us prove (a).

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Proof. Parts (b) and (c) readily follow from the appropriate definitions (the details are left as an easy exercise). Let us prove (a). Set $A = \begin{bmatrix} \mathbf{a}_1 & \dots & \mathbf{a}_m \end{bmatrix}$. To show that $I_n A = A$, we compute (next slide):

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Proof (continued). Reminder: $A = \begin{bmatrix} \mathbf{a}_1 & \dots & \mathbf{a}_m \end{bmatrix}$.

$$\begin{aligned} I_n A &= I_n \begin{bmatrix} \mathbf{a}_1 & \dots & \mathbf{a}_m \end{bmatrix} \\ &= \begin{bmatrix} I_n \mathbf{a}_1 & \dots & I_n \mathbf{a}_m \end{bmatrix} && \text{by the definition of} \\ & && \text{matrix multiplication} \\ &= \begin{bmatrix} \mathbf{a}_1 & \dots & \mathbf{a}_m \end{bmatrix} && \text{by Proposition 1.4.5} \\ &= A. \end{aligned}$$

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Proof (continued). Reminder: $A = \begin{bmatrix} \mathbf{a}_1 & \dots & \mathbf{a}_m \end{bmatrix}$.

On the other hand, to show that $A I_m = A$, we compute:

$$\begin{aligned} A I_m &= A \begin{bmatrix} \mathbf{e}_1^m & \dots & \mathbf{e}_m^m \end{bmatrix} \\ &= \begin{bmatrix} A \mathbf{e}_1^m & \dots & A \mathbf{e}_m^m \end{bmatrix} && \text{by the definition of} \\ & && \text{matrix multiplication} \\ &= \begin{bmatrix} \mathbf{a}_1 & \dots & \mathbf{a}_m \end{bmatrix} && \text{by Proposition 1.4.4} \\ &= A. \end{aligned}$$

This proves (a). \square

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- Then AB is an $n \times p$ matrix whose i, j -th entry is

$$\sum_{k=1}^m a_{i,k} b_{k,j},$$

for all indices $i \in \{1, \dots, n\}$ and $j \in \{1, \dots, p\}$.

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for all indices $i \in \{1, \dots, n\}$ and $j \in \{1, \dots, p\}$.

- Justification: Lecture Notes (not very hard, but notationally a bit messy).
- Another way to write this is as follows:

$$\left[a_{i,j} \right]_{n \times m} \left[b_{i,j} \right]_{m \times p} = \left[\sum_{k=1}^m a_{i,k} b_{k,j} \right]_{n \times p},$$

where in each of the three matrices, the expression between the square brackets is the general form of the i, j -th entry (i.e. the entry in the i -th row and j -th column) of the matrix in question.

- To obtain the i, j -th entry of the matrix AB , we focus on the i -th row of A and j -th column of B .
- We then take the sum of the products of the corresponding entries of this row and column, and we obtain the i, j -th entry of AB .

$$\begin{bmatrix} a_{1,1} & \cdots & a_{1,k} & \cdots & a_{1,m} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ a_{i,1} & \cdots & a_{i,k} & \cdots & a_{i,m} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ a_{n,1} & \cdots & a_{n,k} & \cdots & a_{n,m} \end{bmatrix} \begin{bmatrix} b_{1,1} & \cdots & b_{1,j} & \cdots & b_{1,p} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ b_{k,1} & \cdots & b_{k,j} & \cdots & b_{k,p} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ b_{m,1} & \cdots & b_{m,j} & \cdots & b_{m,p} \end{bmatrix}$$

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Example 1.7.3

Let

$$A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix},$$

with entries understood to be in \mathbb{Z}_2 . Compute the matrix AB .

Solution.

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Solution. We compute as shown below (the rows of A are color coded, as are the columns of B).

$$\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \cdot 1 + 0 \cdot 1 & 1 \cdot 0 + 0 \cdot 1 & 1 \cdot 1 + 0 \cdot 0 \\ 1 \cdot 1 + 1 \cdot 1 & 1 \cdot 0 + 1 \cdot 1 & 1 \cdot 1 + 1 \cdot 0 \end{bmatrix}$$

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with entries understood to be in \mathbb{Z}_2 . Compute the matrix AB .

Solution (continued).

$$\begin{aligned} AB &= \begin{bmatrix} 1 \cdot 1 + 0 \cdot 1 & 1 \cdot 0 + 0 \cdot 1 & 1 \cdot 1 + 0 \cdot 0 \\ 1 \cdot 1 + 1 \cdot 1 & 1 \cdot 0 + 1 \cdot 1 & 1 \cdot 1 + 1 \cdot 0 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}. \end{aligned}$$



Theorem 1.7.5

For any matrices A , B , and C , and any scalars α and β , the following hold (provided the matrices are of compatible size for the operation in question, and the entries of our matrices and our scalars all belong to the same field \mathbb{F}):

- a) $(\alpha + \beta)A = \alpha A + \beta A$;
- b) $(\alpha\beta)A = \alpha(\beta A)$
- c) $A + B = B + A$;
- d) $(A + B) + C = A + (B + C)$;
- e) $(A + B)C = AC + BC$;
- f) $A(B + C) = AB + AC$;
- g) $(AB)C = A(BC)$;
- h) $(\alpha A)B = \alpha(AB)$;
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Proof of (g). Fix matrices $A = \begin{bmatrix} a_{i,j} \end{bmatrix}_{n_1 \times n_2}$ in $\mathbb{F}^{n_1 \times n_2}$,
 $B = \begin{bmatrix} b_{i,j} \end{bmatrix}_{n_2 \times n_3}$ in $\mathbb{F}^{n_2 \times n_3}$, and $C = \begin{bmatrix} c_{i,j} \end{bmatrix}_{n_3 \times n_4}$ in $\mathbb{F}^{n_3 \times n_4}$.

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Clearly, both $(AB)C$ and $A(BC)$ are matrices in $\mathbb{F}^{n_1 \times n_4}$.

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$$(g) \quad (AB)C = A(BC)$$

Proof of (g) (continued). We first compute the i, j -th entry of $(AB)C$.

$$(g) (AB)C = A(BC)$$

Proof of (g) (continued). We first compute the i, j -th entry of $(AB)C$. The i -th row of the $n_1 \times n_3$ matrix AB is

$$\left[\sum_{k=1}^{n_2} a_{i,k} b_{k,1} \quad \sum_{k=1}^{n_2} a_{i,k} b_{k,2} \quad \dots \quad \sum_{k=1}^{n_2} a_{i,k} b_{k,n_3} \right].$$

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 The j -th column

of the $n_3 \times n_4$ matrix C is $\begin{bmatrix} c_{1,j} \\ c_{2,j} \\ \vdots \\ c_{n_3,j} \end{bmatrix}$.

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So, the i, j -th entry of the $n_1 \times n_4$ matrix $(AB)C$ is

$$\sum_{\ell=1}^{n_3} \left(\left(\sum_{k=1}^{n_2} a_{i,k} b_{k,\ell} \right) c_{\ell,j} \right).$$

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Proof of (g) (continued). We now compute the i, j -th entry of $A(BC)$. The i -th row of the $n_1 \times n_2$ matrix A is

$$\left[a_{i,1} \quad a_{i,2} \quad \cdots \quad a_{i,n_2} \right].$$

$$(g) (AB)C = A(BC)$$

Proof of (g) (continued). We now compute the i, j -th entry of $A(BC)$. The i -th row of the $n_1 \times n_2$ matrix A is

$\left[a_{i,1} \ a_{i,2} \ \dots \ a_{i,n_2} \right]$. The j -th column of the $n_2 \times n_4$ matrix

$$BC \text{ is } \begin{bmatrix} \sum_{k=1}^{n_3} b_{1,k} c_{k,j} \\ \sum_{k=1}^{n_3} b_{2,k} c_{k,j} \\ \vdots \\ \sum_{k=1}^{n_3} b_{n_2,k} c_{k,j} \end{bmatrix}.$$

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Proof of (g) (continued). Reminder:

- the i, j -th entry of $(AB)C$ is $\sum_{\ell=1}^{n_3} \left(\left(\sum_{k=1}^{n_2} a_{i,k} b_{k,\ell} \right) c_{\ell,j} \right)$;
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It now remains to show that

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For this, we compute (next slide):

(g) $(AB)C = A(BC)$

Proof of (g) (continued).

$$\begin{aligned} \sum_{\ell=1}^{n_3} \left(\left(\sum_{k=1}^{n_2} a_{i,k} b_{k,\ell} \right) c_{\ell,j} \right) &= \sum_{\ell=1}^{n_3} \left(\sum_{k=1}^{n_2} a_{i,k} b_{k,\ell} c_{\ell,j} \right) \\ &= \sum_{k=1}^{n_2} \left(\sum_{\ell=1}^{n_3} a_{i,k} b_{k,\ell} c_{\ell,j} \right) \\ &= \sum_{k=1}^{n_2} \left(a_{i,k} \left(\sum_{\ell=1}^{n_3} b_{k,\ell} c_{\ell,j} \right) \right) \\ &= \sum_{\ell=1}^{n_2} \left(a_{i,\ell} \left(\sum_{k=1}^{n_3} b_{\ell,k} c_{k,j} \right) \right) \end{aligned}$$

and we obtain the equality that we needed. This proves (g). \square

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- In fact, it is possible that one of AB and BA is defined, while the other one is not.
 - For instance, if $A \in \mathbb{F}^{2 \times 3}$ and $B \in \mathbb{F}^{3 \times 4}$, where \mathbb{F} is some field, then AB is defined, but BA is not.

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$$AB \neq BA.$$

- In fact, it is possible that one of AB and BA is defined, while the other one is not.
 - For instance, if $A \in \mathbb{F}^{2 \times 3}$ and $B \in \mathbb{F}^{3 \times 4}$, where \mathbb{F} is some field, then AB is defined, but BA is not.
- Moreover, it is possible that both AB and BA are defined, but are not of the same size.
 - For instance, if $A \in \mathbb{F}^{2 \times 3}$ and $B \in \mathbb{F}^{3 \times 2}$, where \mathbb{F} is some field, then $AB \in \mathbb{F}^{2 \times 2}$ and $BA \in \mathbb{F}^{3 \times 3}$.

- **Warning:** Matrix multiplication is **not** commutative, that is, for matrices A and B ,

$$AB \neq BA.$$

- In fact, it is possible that one of AB and BA is defined, while the other one is not.
 - For instance, if $A \in \mathbb{F}^{2 \times 3}$ and $B \in \mathbb{F}^{3 \times 4}$, where \mathbb{F} is some field, then AB is defined, but BA is not.
- Moreover, it is possible that both AB and BA are defined, but are not of the same size.
 - For instance, if $A \in \mathbb{F}^{2 \times 3}$ and $B \in \mathbb{F}^{3 \times 2}$, where \mathbb{F} is some field, then $AB \in \mathbb{F}^{2 \times 2}$ and $BA \in \mathbb{F}^{3 \times 3}$.
- Finally, it is possible that AB and BA are both defined, and are of the same size, but $AB \neq BA$.
 - For example, for $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$, we have that $AB = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$ and $BA = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$, and so $AB \neq BA$.

Corollary 1.7.6

For any matrices A , B , vectors \mathbf{u} , \mathbf{v} , and \mathbf{w} , and scalars α and β , the following hold (provided the matrices and vectors are of compatible size for the operation in question, and the entries of our matrices, the entries of our vectors, and our scalars all belong to the same field \mathbb{F}):

- a) $(\alpha + \beta)\mathbf{u} = \alpha\mathbf{u} + \beta\mathbf{u}$;
- b) $(\alpha\beta)\mathbf{u} = \alpha(\beta\mathbf{u})$
- c) $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$;
- d) $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$;
- e) $(A + B)\mathbf{u} = A\mathbf{u} + B\mathbf{u}$;
- f) $A(\mathbf{u} + \mathbf{v}) = A\mathbf{u} + A\mathbf{v}$;
- g) $(AB)\mathbf{u} = A(B\mathbf{u})$;
- h) $(\alpha A)\mathbf{u} = \alpha(A\mathbf{u})$;
- i) $A(\alpha\mathbf{u}) = \alpha(A\mathbf{u})$.

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- For a field \mathbb{F} and a square matrix $A \in \mathbb{F}^{n \times n}$, we define
 - $A^0 := I_n$;
 - $A^{m+1} := A^m A$ for all non-negative integers m .
- So, by convention, we set $A^0 := I_n$, and for any positive integer m , we have that

$$A^m = \underbrace{A \dots A}_m,$$

where we did not have to indicate parentheses since, by Theorem 1.7.5, matrix multiplication is associative.

6 The transpose of a matrix

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- Given a matrix $A \in \mathbb{F}^{n \times m}$ (where \mathbb{F} is a field), the *transpose* of A , denoted by A^T , is the matrix in $\mathbb{F}^{m \times n}$ s.t. the i, j -th entry of A^T is the j, i -th entry of A , for all indices $i \in \{1, \dots, m\}$ and $j \in \{1, \dots, n\}$.

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- In other words, to form A^T from A , the columns of A (from left to right) become the rows of A^T (from top to bottom), and likewise, the rows of A (from top to bottom) become the columns of A^T (from left to right).

$$A = \begin{bmatrix} \color{red}{\blacklozenge} & * & * & * & * & \color{red}{\blacklozenge} \\ \color{blue}{\blacklozenge} & * & * & * & * & \color{blue}{\blacklozenge} \\ \color{green}{\blacklozenge} & * & * & * & * & \color{green}{\blacklozenge} \\ \color{purple}{\blacklozenge} & * & * & * & * & \color{purple}{\blacklozenge} \end{bmatrix} \quad \longrightarrow \quad A^T = \begin{bmatrix} \color{red}{\blacklozenge} & \color{blue}{\blacklozenge} & \color{green}{\blacklozenge} & \color{purple}{\blacklozenge} \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \\ \color{red}{\blacklozenge} & \color{blue}{\blacklozenge} & \color{green}{\blacklozenge} & \color{purple}{\blacklozenge} \end{bmatrix}$$

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- For example, if $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$, then $A^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$.

- In order to save space, we often specify column vectors in terms of transposes of row vectors.
- For instance, we often write something like

$$\mathbf{u} = \left[u_1 \quad u_2 \quad \dots \quad u_n \right]^T \text{ instead of } \mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix}.$$

Proposition 1.8.1

For any matrices A and B , and any scalar α , the following hold (provided the matrices are of compatible size for the operation in question, and the entries of our matrices and our scalar belong to the same field \mathbb{F}):

Ⓐ $(A^T)^T = A;$

Ⓒ $(\alpha A)^T = \alpha A^T$

Ⓑ $(A + B)^T = A^T + B^T;$

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Proof. Parts (a), (b), and (c) are obvious. Let us prove (d). Fix matrices $A \in \mathbb{F}^{n \times m}$ and $B \in \mathbb{F}^{m \times p}$, and set $A = \begin{bmatrix} a_{i,j} \end{bmatrix}_{n \times m}$ and $B = \begin{bmatrix} b_{i,j} \end{bmatrix}_{m \times p}$.

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(c) $(\alpha A)^T = \alpha A^T$

(b) $(A + B)^T = A^T + B^T$;

(d) $(AB)^T = B^T A^T$.

Proof. Parts (a), (b), and (c) are obvious. Let us prove (d). Fix matrices $A \in \mathbb{F}^{n \times m}$ and $B \in \mathbb{F}^{m \times p}$, and set $A = \begin{bmatrix} a_{i,j} \end{bmatrix}_{n \times m}$ and $B = \begin{bmatrix} b_{i,j} \end{bmatrix}_{m \times p}$. Clearly, $AB \in \mathbb{F}^{n \times p}$, and so $(AB)^T \in \mathbb{F}^{p \times n}$.

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$$(d) (AB)^T = B^T A^T$$

Proof of (d) (continued).

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Proof of (d) (continued). Fix indices $i \in \{1, \dots, p\}$ and $j \in \{1, \dots, n\}$; we will show that the i, j -th entry of $(AB)^T$ is equal to the i, j -th entry of $B^T A^T$.

By the definition of matrix transpose, the i, j -th entry of $(AB)^T$ is equal to the j, i -th entry of AB , which is equal to $\sum_{k=1}^m a_{j,k} b_{k,i}$.

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We now compute the i, j -th entry of $B^T A^T$.

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We now compute the i, j -th entry of $B^T A^T$. We observe that i -th row of the matrix B^T is $\begin{bmatrix} b_{1,i} & b_{2,i} & \dots & b_{m,i} \end{bmatrix}$, whereas the j -th column of the matrix A^T is $\begin{bmatrix} a_{j,1} & a_{j,2} & \dots & a_{j,m} \end{bmatrix}^T$.

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$$b_{1,i} a_{j,1} + b_{2,i} a_{j,2} + \dots + b_{m,i} a_{j,m} = \sum_{k=1}^m b_{k,i} a_{j,k} = \sum_{k=1}^m a_{j,k} b_{k,i}.$$

$$(d) (AB)^T = B^T A^T$$

Proof of (d) (continued). Fix indices $i \in \{1, \dots, p\}$ and $j \in \{1, \dots, n\}$; we will show that the i, j -th entry of $(AB)^T$ is equal to the i, j -th entry of $B^T A^T$.

By the definition of matrix transpose, the i, j -th entry of $(AB)^T$ is equal to the j, i -th entry of AB , which is equal to $\sum_{k=1}^m a_{j,k} b_{k,i}$.

We now compute the i, j -th entry of $B^T A^T$. We observe that i -th row of the matrix B^T is $\begin{bmatrix} b_{1,i} & b_{2,i} & \dots & b_{m,i} \end{bmatrix}$, whereas the j -th column of the matrix A^T is $\begin{bmatrix} a_{j,1} & a_{j,2} & \dots & a_{j,m} \end{bmatrix}^T$. So, the i, j -th entry of the matrix $B^T A^T$ is

$$b_{1,i} a_{j,1} + b_{2,i} a_{j,2} + \dots + b_{m,i} a_{j,m} = \sum_{k=1}^m b_{k,i} a_{j,k} = \sum_{k=1}^m a_{j,k} b_{k,i}.$$

We have now shown that the corresponding entries of the $p \times n$ matrices $(AB)^T$ and $B^T A^T$ are the same, and we deduce that $(AB)^T = B^T A^T$. This proves (d). \square

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