

Linear Algebra 1: Tutorial 4

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Winter 2022/2023

Exercise 1. Determine which of the following functions are linear (and prove your answer is correct). For those that are linear, find their standard matrix.

(a) $f_1 : \mathbb{R}^2 \rightarrow \mathbb{R}^2$, given by $f_1\left(\begin{bmatrix} u_1 \\ u_2 \end{bmatrix}\right) = \begin{bmatrix} \frac{1}{2}u_1 + \frac{1}{3}u_2 \\ 3u_1 \end{bmatrix}$ for all $u_1, u_2 \in \mathbb{R}$.

(b) $f_2 : \mathbb{R}^3 \rightarrow \mathbb{R}^4$, given by $f_2\left(\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}\right) = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ 1 \end{bmatrix}$ for all $u_1, u_2, u_3 \in \mathbb{R}$.

(c) $f_3 : \mathbb{Z}_2^2 \rightarrow \mathbb{Z}_2^2$, given by $f_3\left(\begin{bmatrix} u_1 \\ u_2 \end{bmatrix}\right) = \begin{bmatrix} u_1 \\ u_2^2 \end{bmatrix}$ for all $u_1, u_2 \in \mathbb{Z}_2$.

(d) $f_4 : \mathbb{Z}_3^2 \rightarrow \mathbb{Z}_3^2$, given by $f_4\left(\begin{bmatrix} u_1 \\ u_2 \end{bmatrix}\right) = \begin{bmatrix} u_1 \\ u_2^2 \end{bmatrix}$ for all $u_1, u_2 \in \mathbb{Z}_3$.

Exercise 2. For each of the following matrices, determine whether it is invertible, and if so, find its inverse.

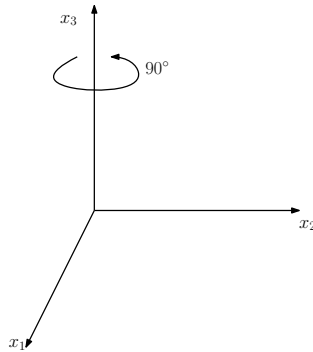
(a) $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 5 \end{bmatrix}$, with entries understood to be in \mathbb{R} .

(b) $B = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$, with entries understood to be in \mathbb{Z}_2 .

(c) $C = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 2 & 2 & 1 \end{bmatrix}$, with entries understood to be in \mathbb{Z}_3 .

Exercise 3. Find the standard matrices of the following linear transformations (you may assume they are linear).

(a) $f : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ that rotates each vector about the x_3 axis by 90° counterclockwise.

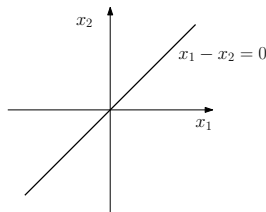


(b) $g : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ that projects each vector onto the x_1x_3 -plane.

(c) $h_1 : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ that first rotates each vector about the x_3 axis by 90° counterclockwise, and then projects each vector onto the x_1x_3 -plane.

(d) $h_2 : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ that first projects each vector onto the x_1x_3 -plane, and then rotates each vector about the x_3 axis by 90° counterclockwise.

Exercise 4. Find the standard matrix of the linear transformation $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ that projects each vector onto the line given by the equation $x_1 - x_2 = 0$ (you may assume the transformation is linear).



Exercise 5. Explain why the function $g : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ that projects each vector onto the line $x_1 + x_2 = 1$ is **not** linear.

